

模块化的三相多电平功率因数校正技术

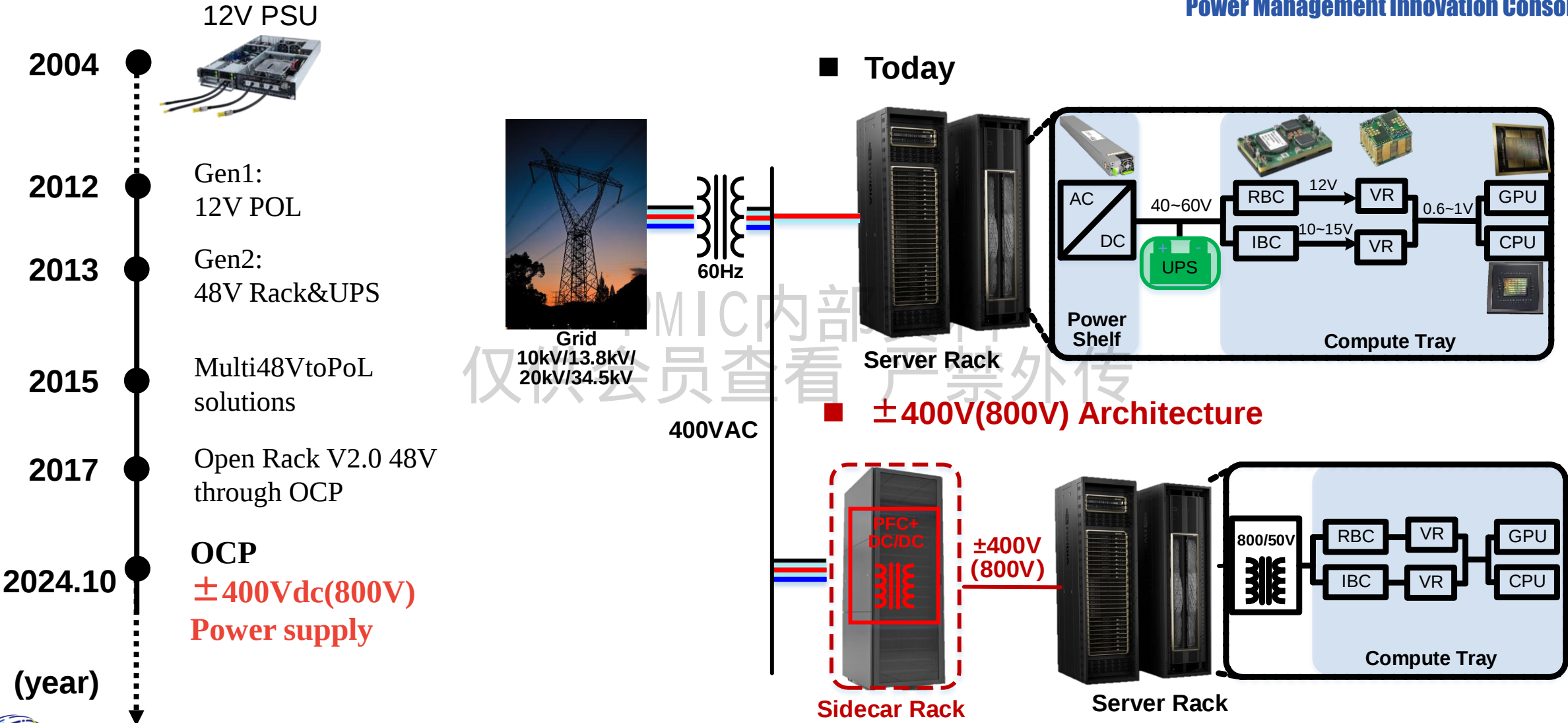
Modularized Three-phase Multilevel Power Factor Correction Technology

汇报人：吴新科 赵问鼎

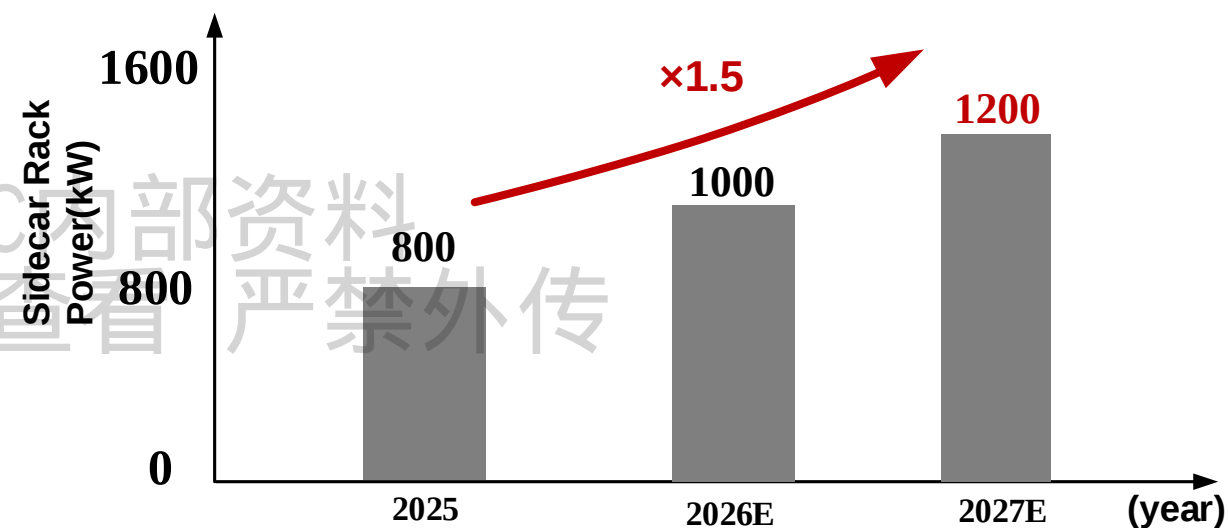
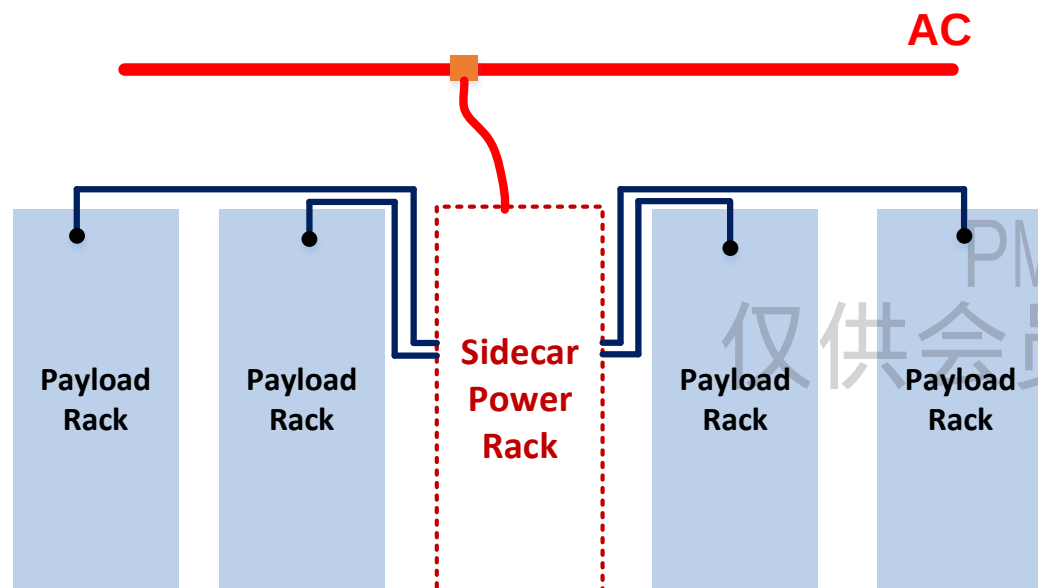
Server Power Architecture Develops towards $\pm 400\text{V}(800\text{V})$



Power Management Innovation Consortium



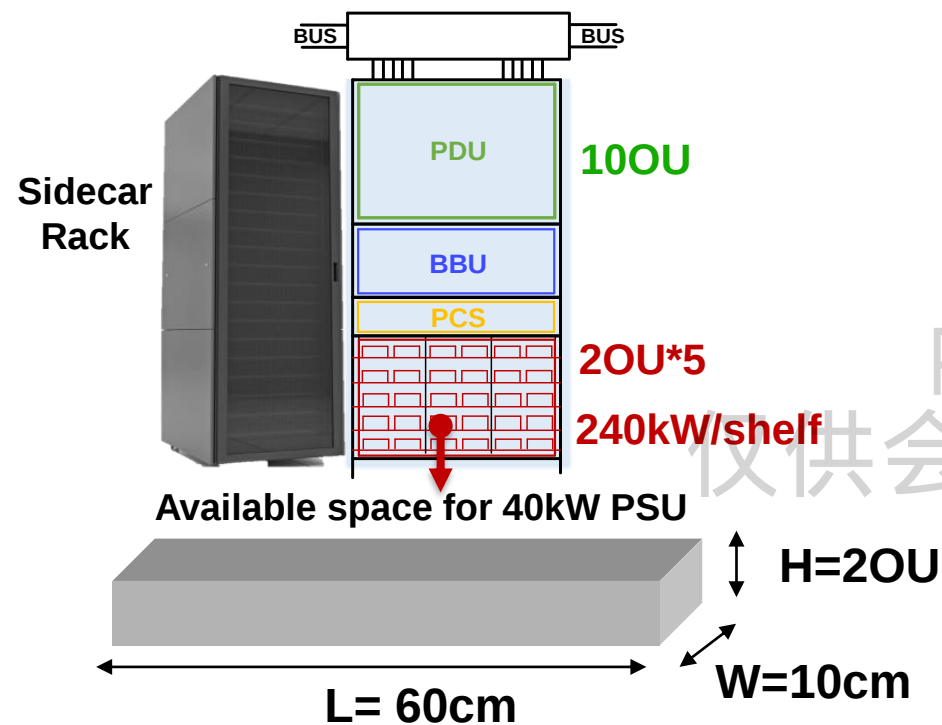
Trend of Sidecar Rack Power



➤ The power of server rack has been rapidly increasing

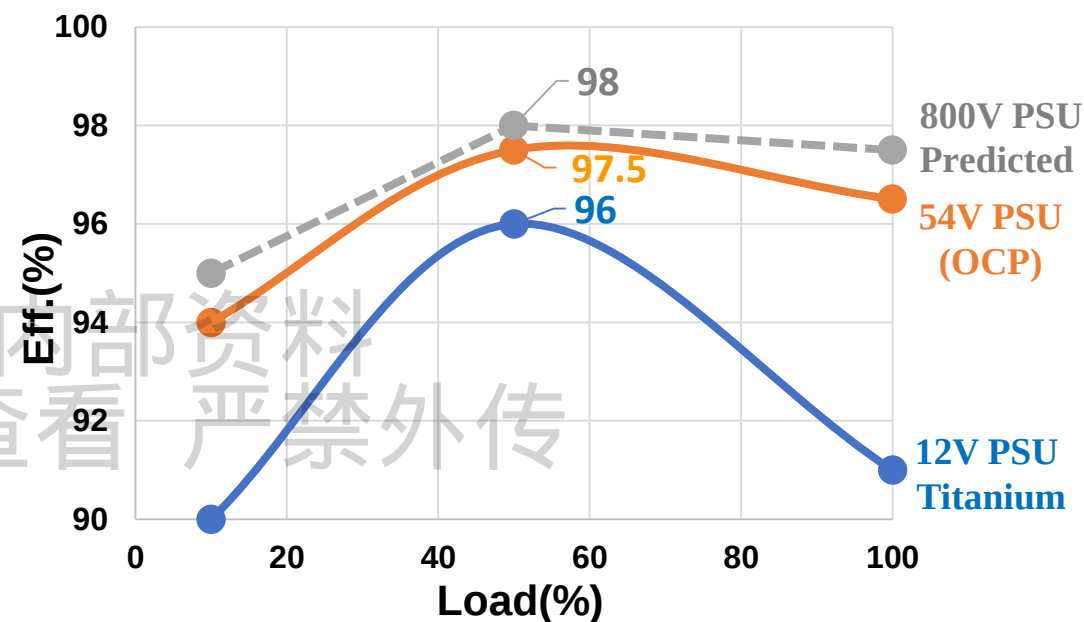
High Efficiency High Density for Server PSU

➤ High Power Density

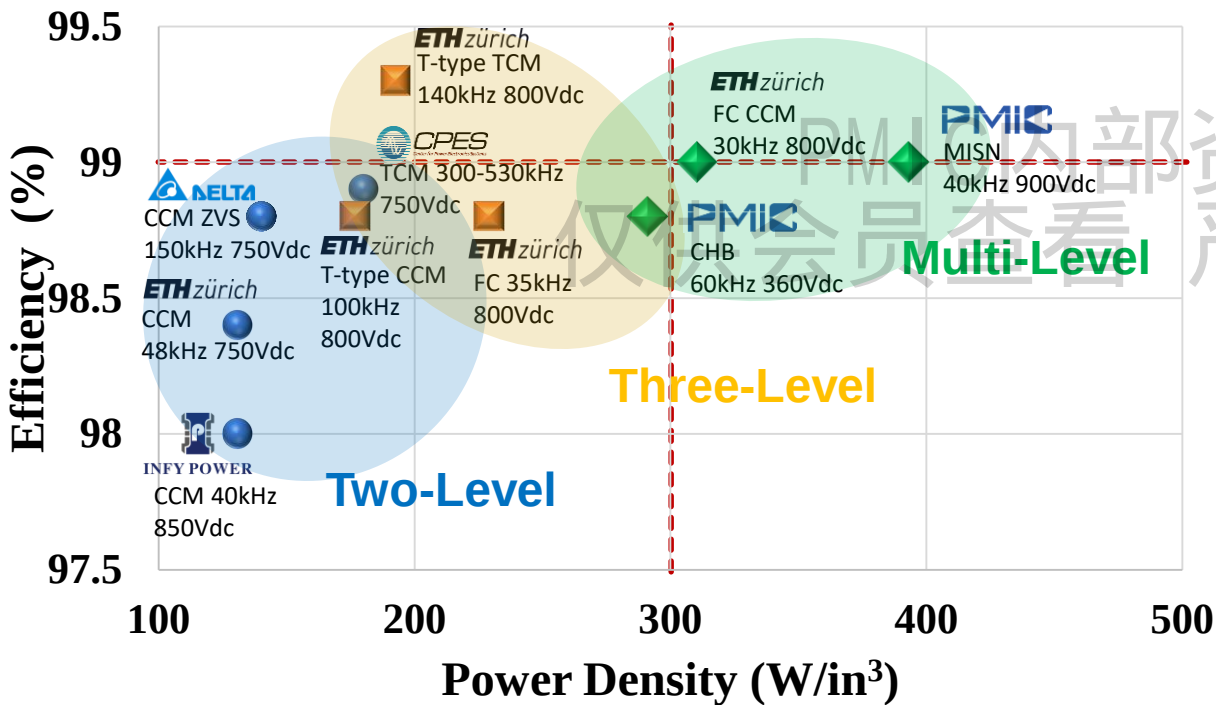
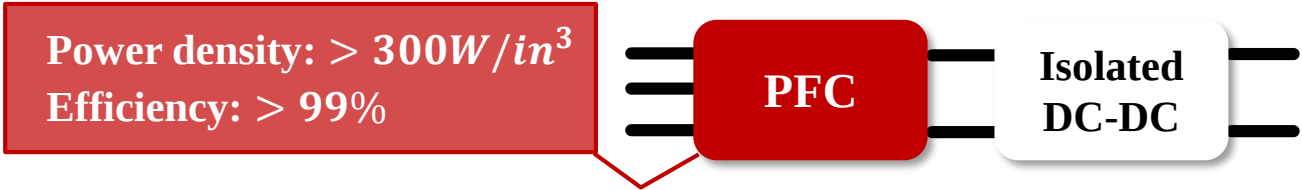


Power Density: $>150\text{W}/\text{in}^3$

➤ High Efficiency

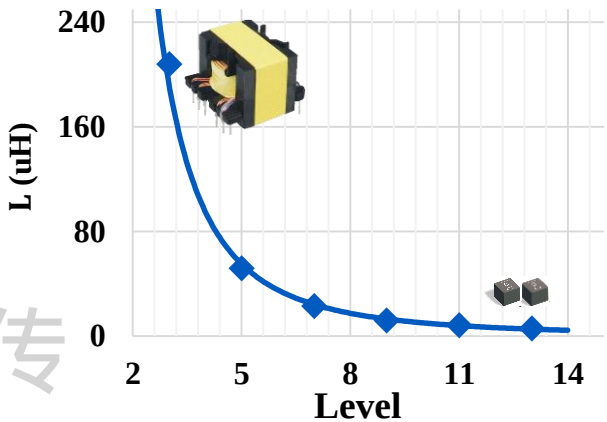


Efficiency: $>98\%$

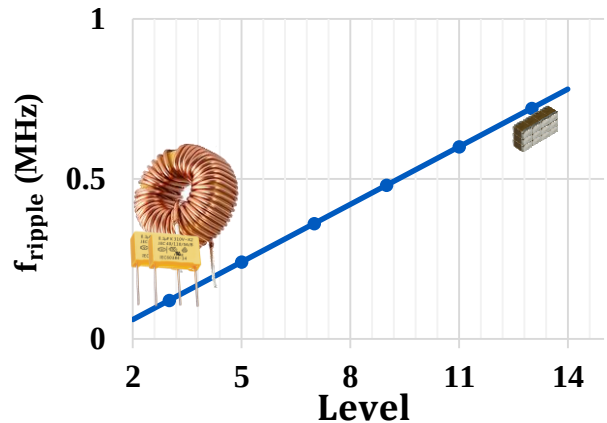


➤ The Influence of Multilevel Converter

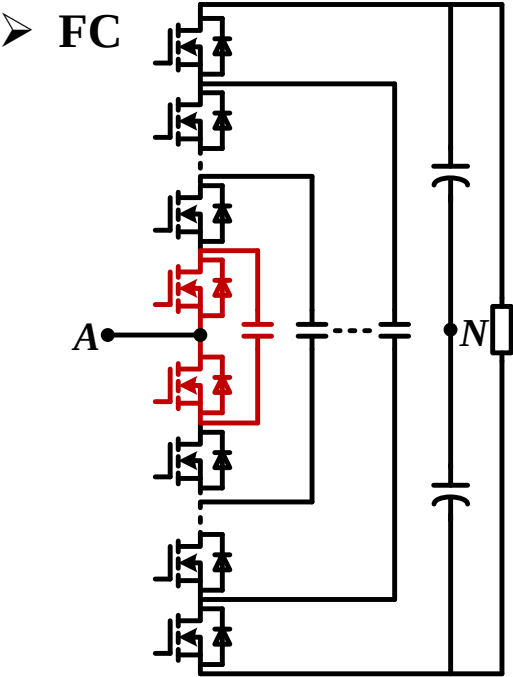
- Lower Volt-second



- Higher Frequency

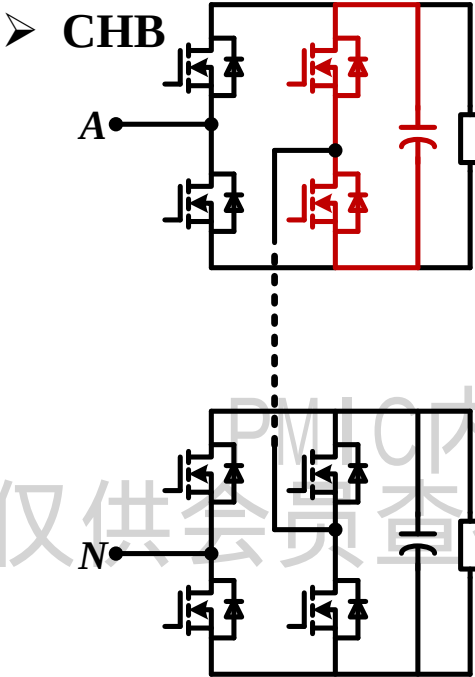


Comparison the Different Multilevel Topologies



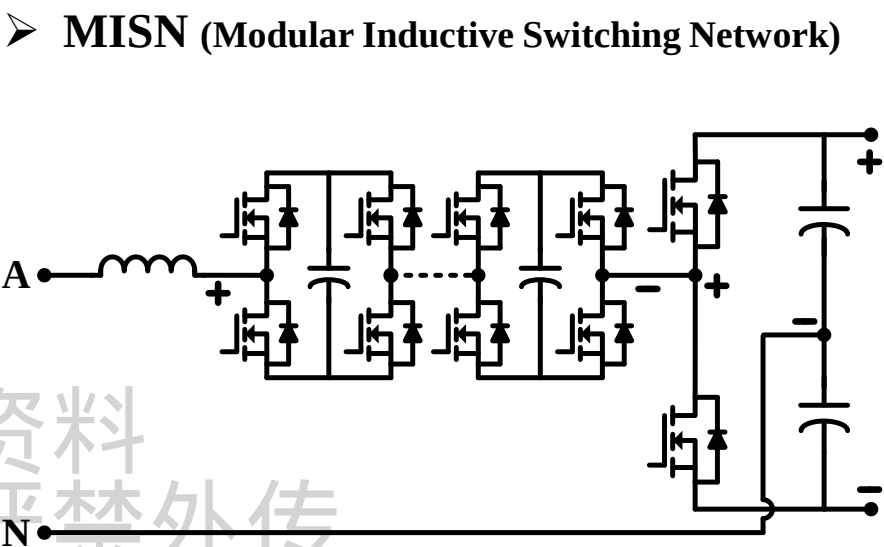
✓ Single DC Bus

✗ Bad Modularity
Short fault protect
Redundancy



✓ Good Modularity

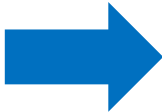
✗ Multiple DC Bus
Complicated structure
Bulky Capacitor



✓ Single DC Bus

✓ Good Modularity
✗ Line-frequency Bridge

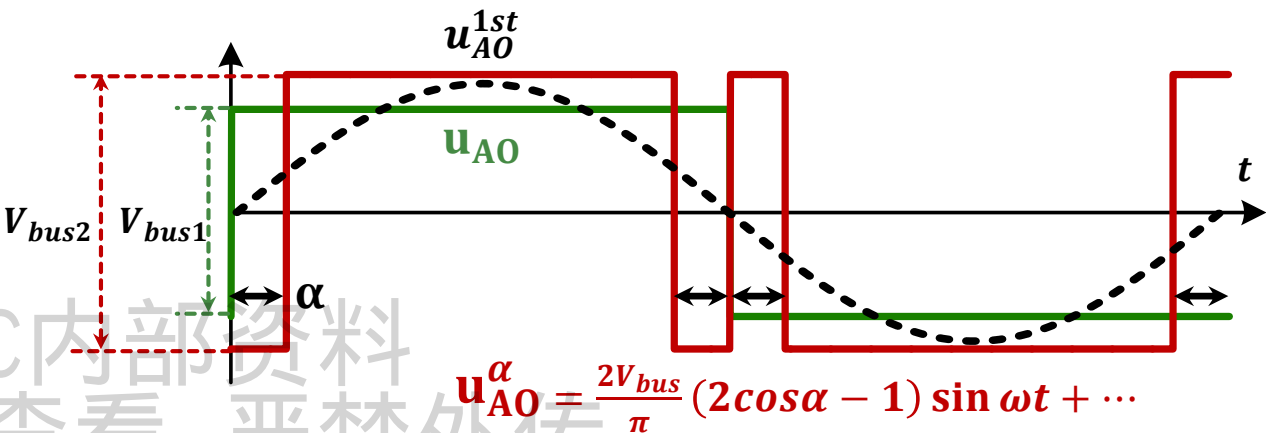
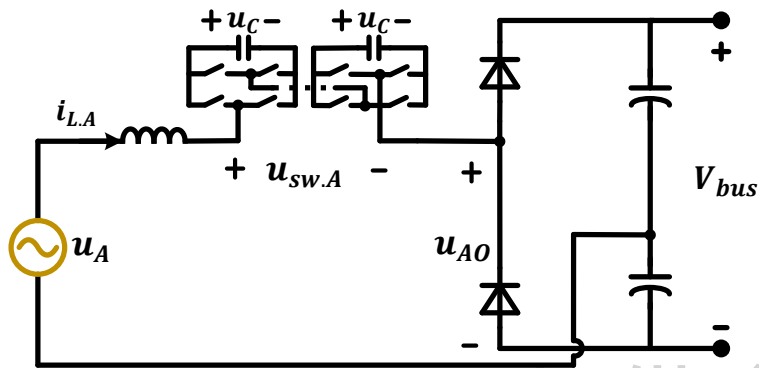


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- 1 三相MISN-PFC变换器的控制策略研究
 - 2 三相MISN-PFC变换器的优化设计研究
 - 3 三相MISN-PFC变换器的极轻载控制研究

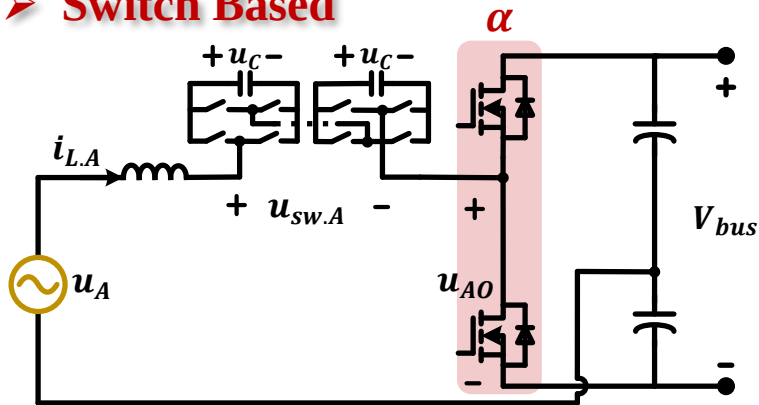
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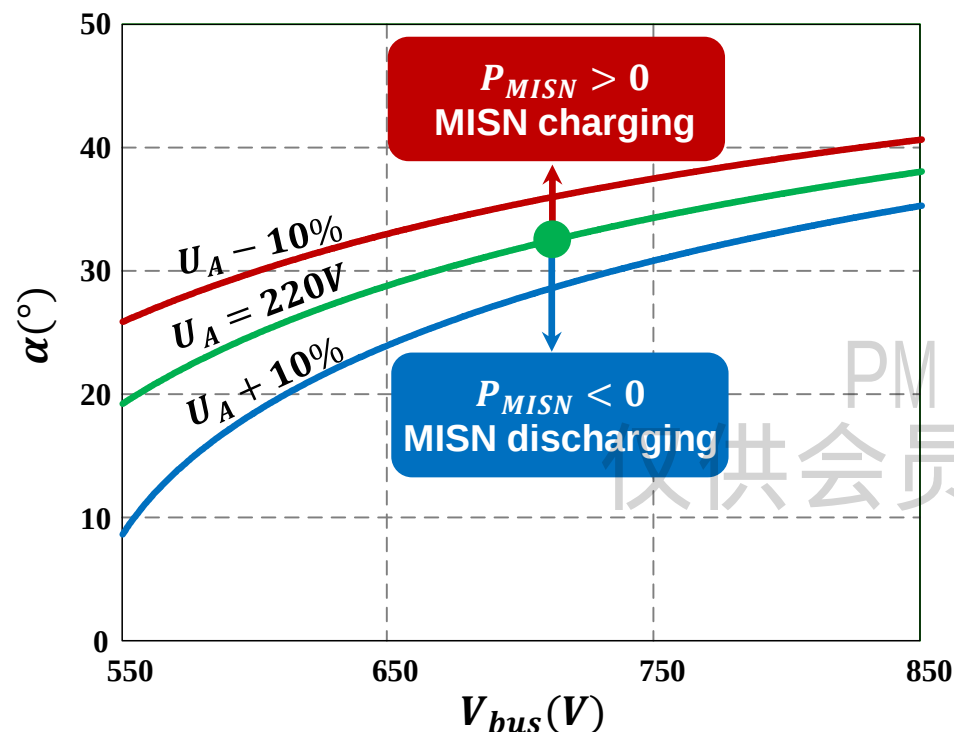
➤ Diode Based $(V_o = \frac{\pi}{\sqrt{2}} U_A)$



➤ Switch Based



$$\alpha = \arccos\left(\frac{\sqrt{2}\pi U_A}{4V_{bus}} + \frac{1}{2}\right)$$



$$P_{MISN} = \frac{1}{2\pi} \int_0^{2\pi} p_{MISN} d\omega t = \frac{\sqrt{2}I_L}{\pi} (\sqrt{2}\pi U_A - 2V_{bus})$$

➤ In the curve

$P_{MISN} = 0$, Power balance

➤ Above the curve

$P_{MISN} > 0$, Charging mode

➤ Below the curve

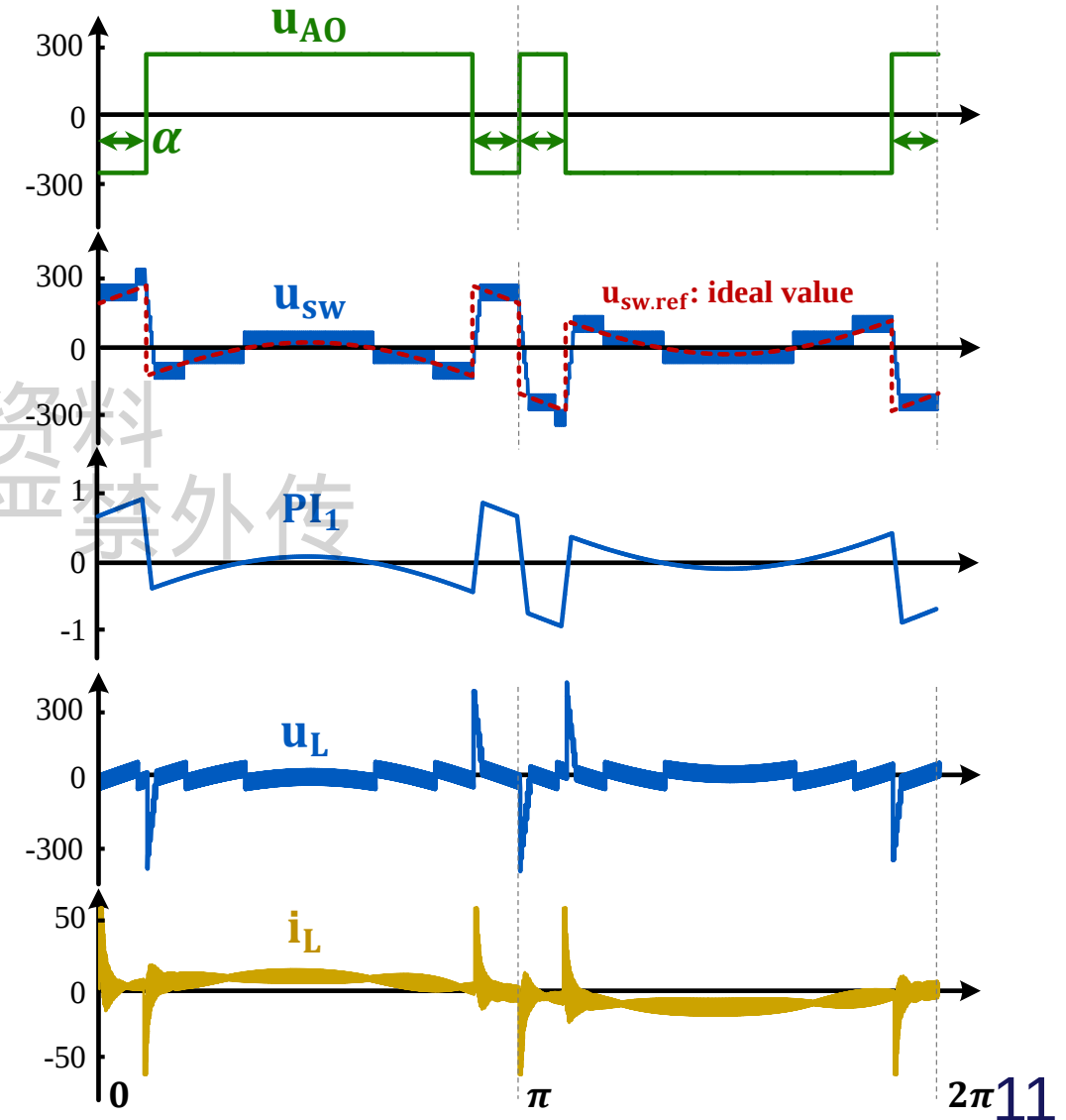
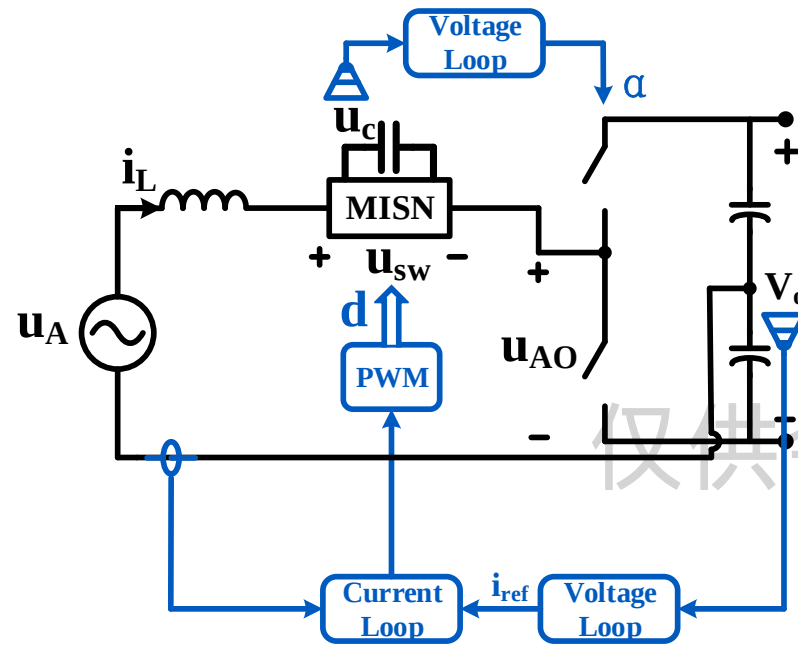
$P_{MISN} < 0$, Discharging mode

Utilized for MISN voltage Control

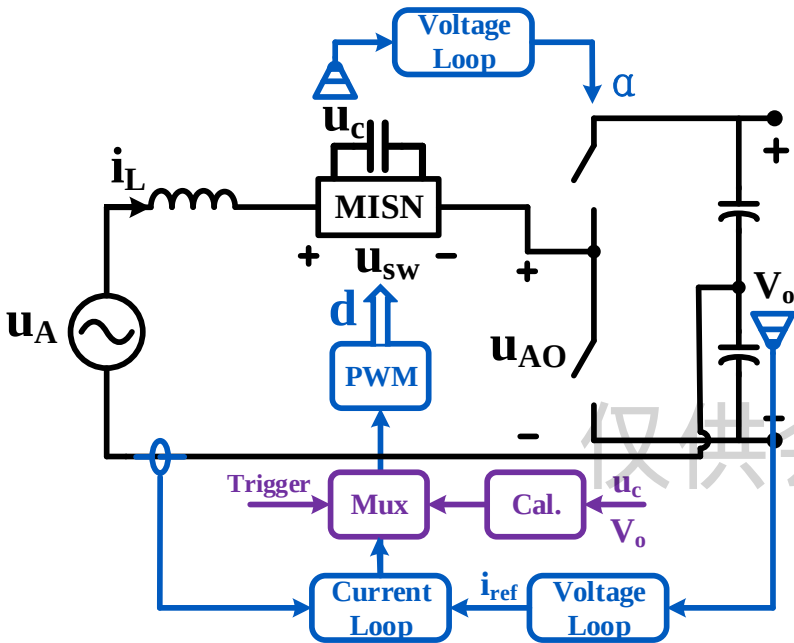
$$\alpha = \arccos \left(\frac{\sqrt{2}\pi U_A}{4V_{bus}} + \frac{1}{2} \right)$$

Current Distortion due to the Limited Bandwidth of Current Loop

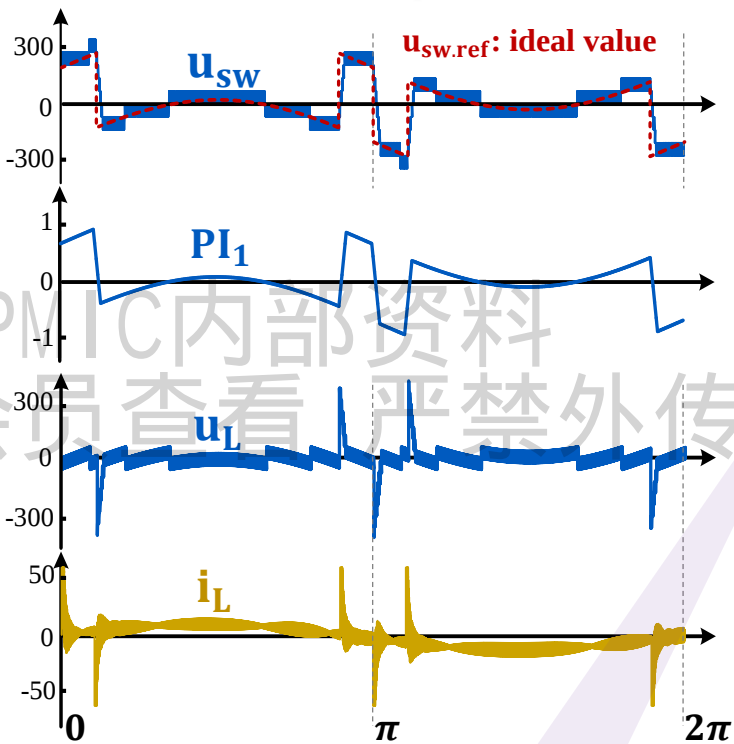
➤ The Control Strategy of Phase-A



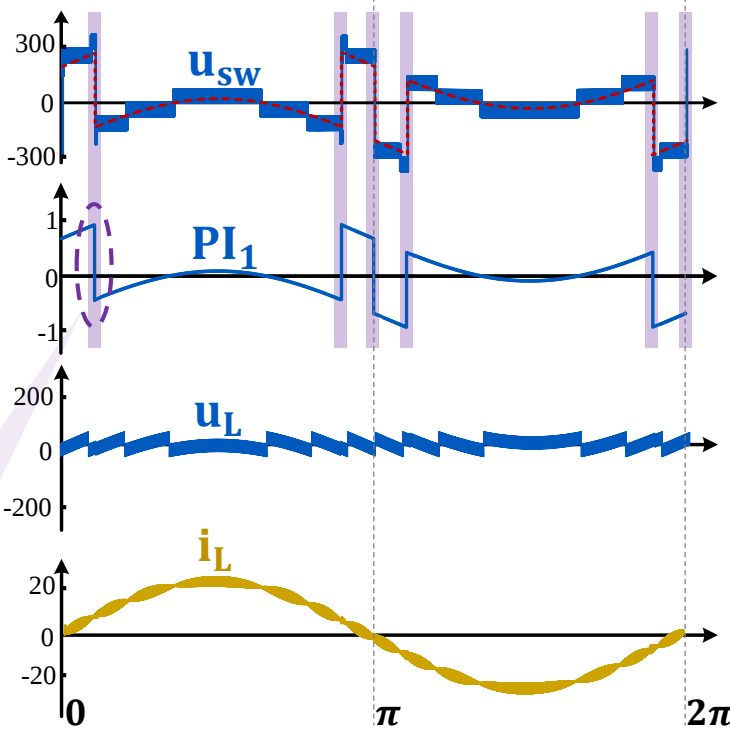
➤ The Control Strategy of Phase-A



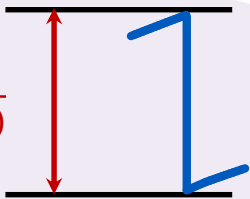
● Without Transient Compensation



● With Transient Compensation

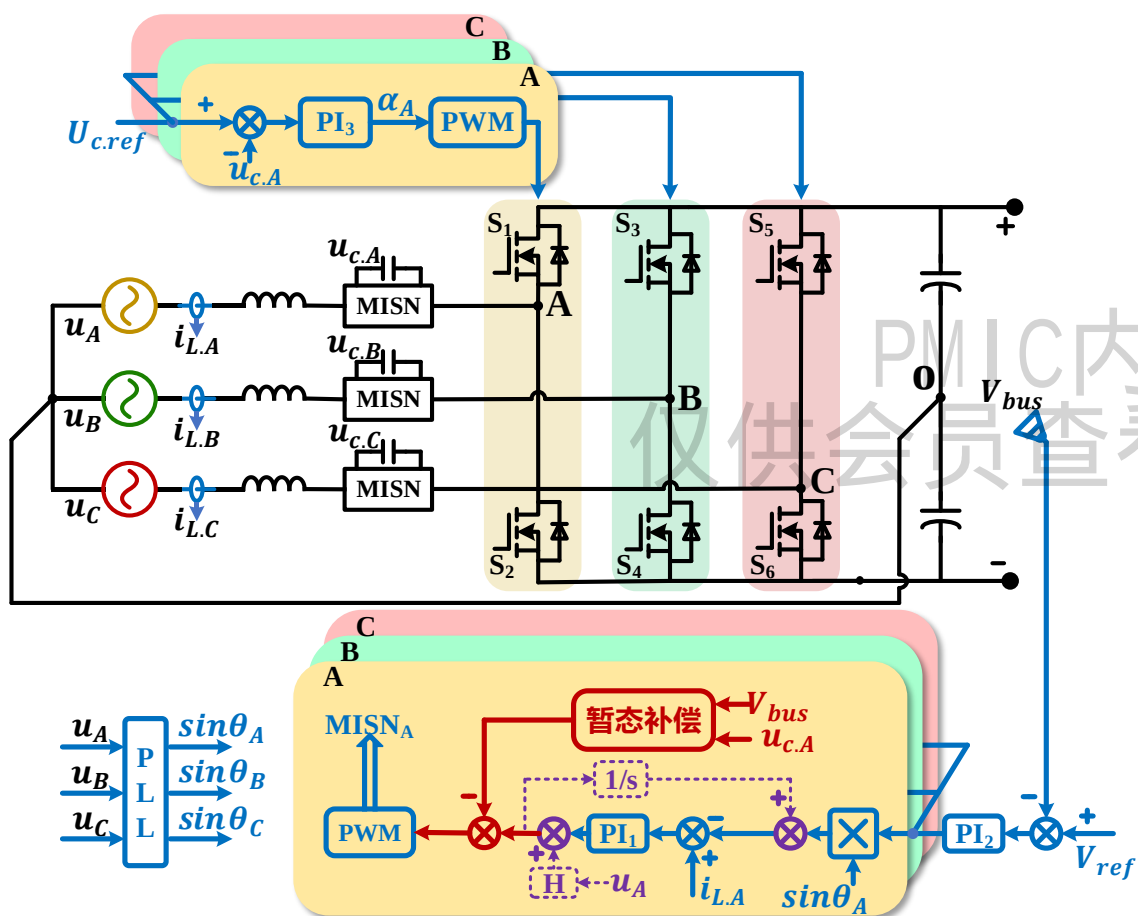


$$\Delta PI(t) = \frac{v_o(t)}{2u_{c.total}(t)}$$

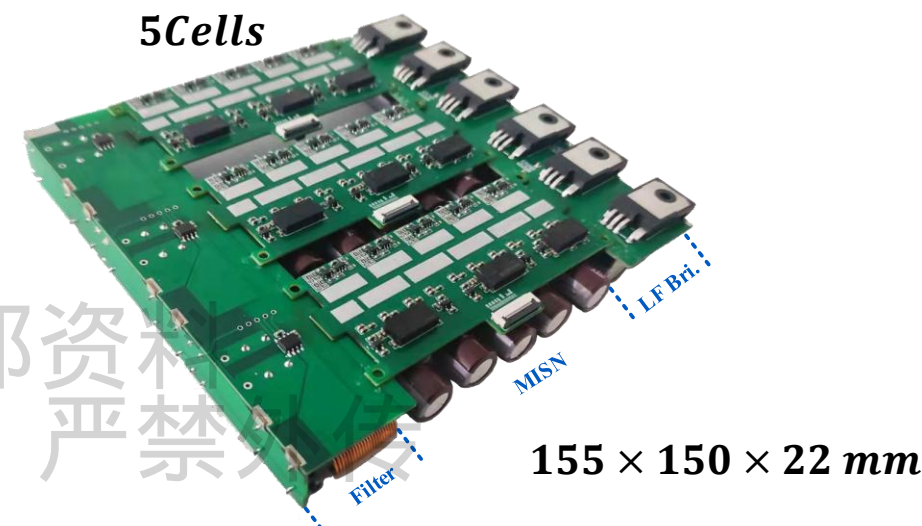


The Steady State Operation at 10kW

➤ Control Strategy of 3phase MISN-PFC converter



➤ 10kW Hardware Implementation



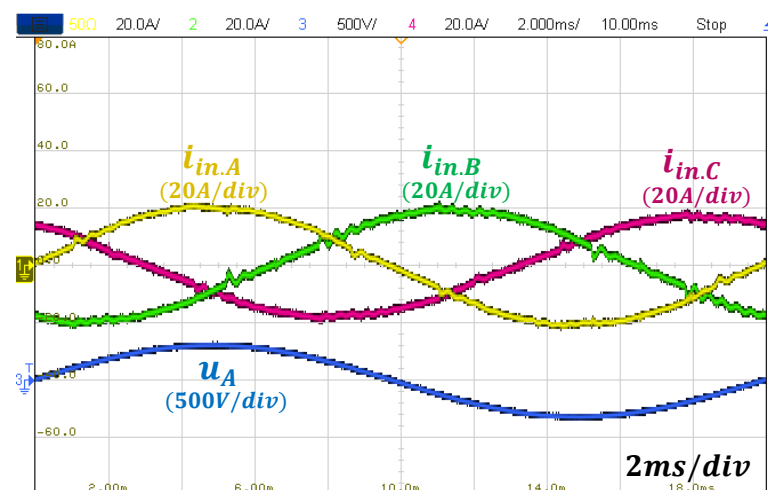
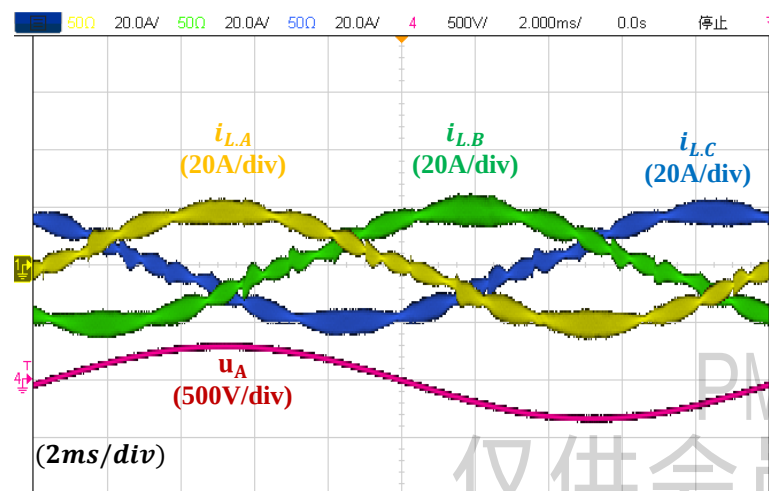
Power Density: 330W/in³

Input Phase Voltage: 220V_{ac} ± 10%

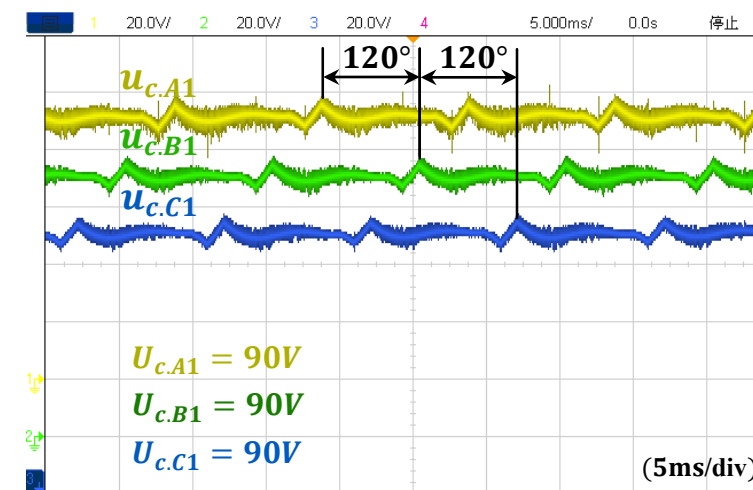
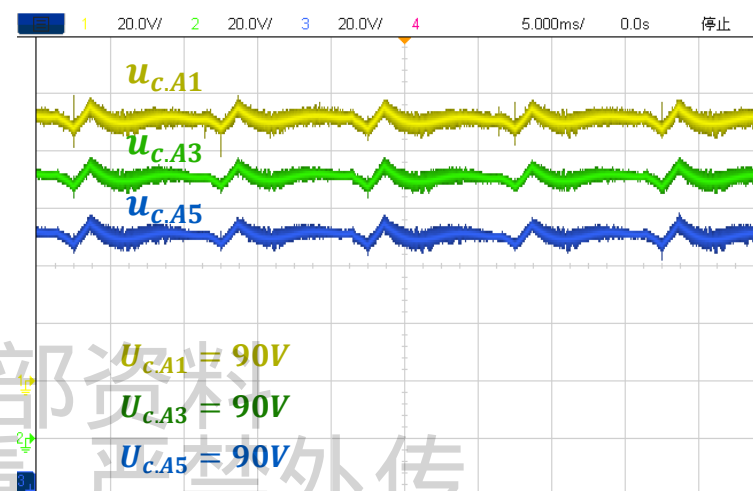
DC Bus Voltage: 550V

Rated Power: 10kW

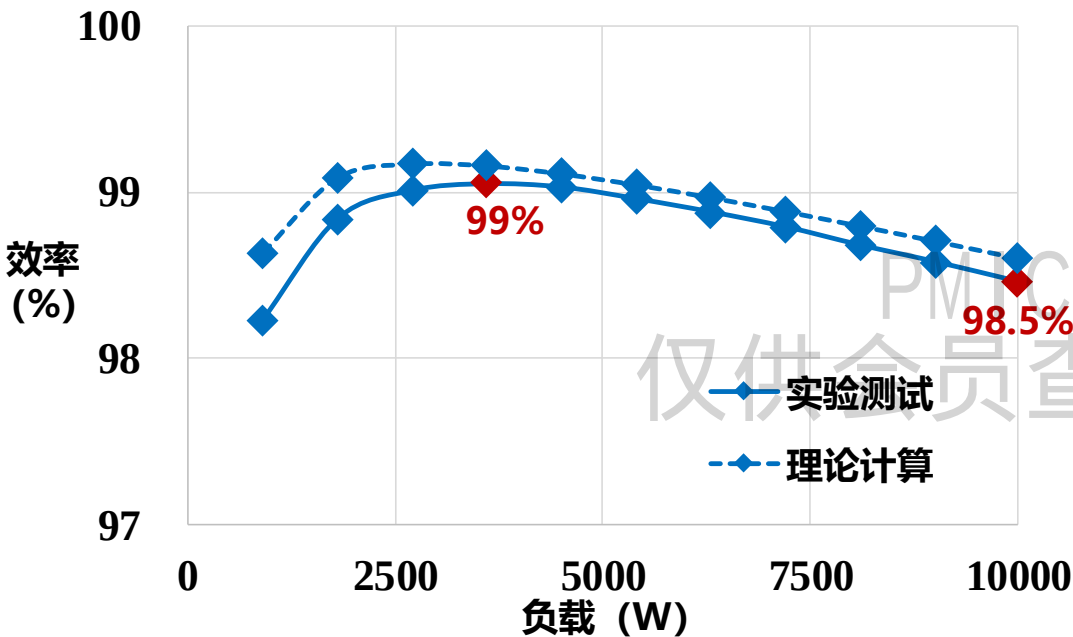
➤ 3-phase Currents



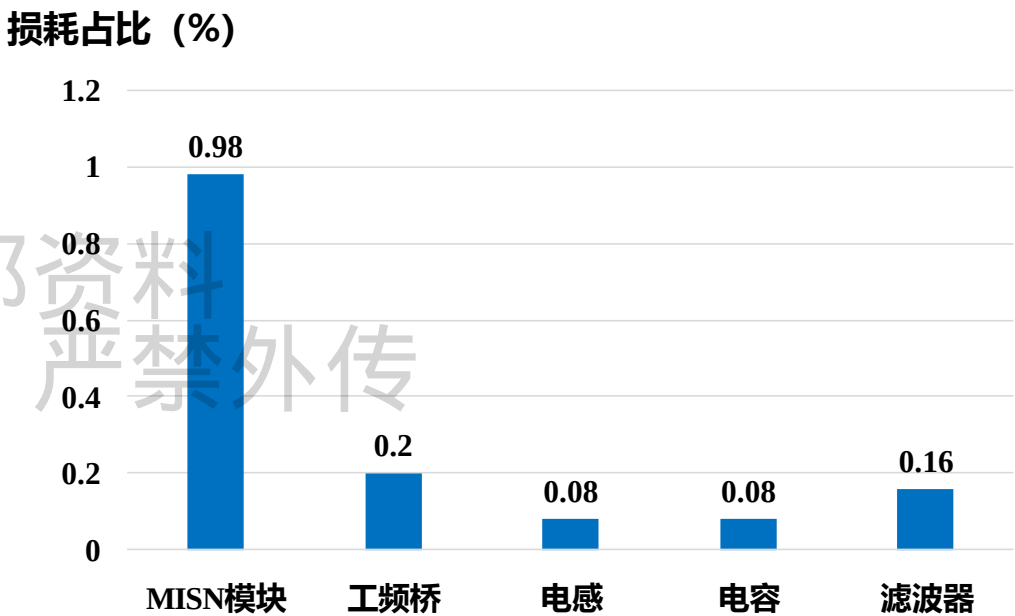
➤ 3-phase MISN Capacitors' Voltages



➤ Efficiency under different load



➤ Loss breakdown under full load



1

三相MISN-PFC变换器的控制策略研究

2

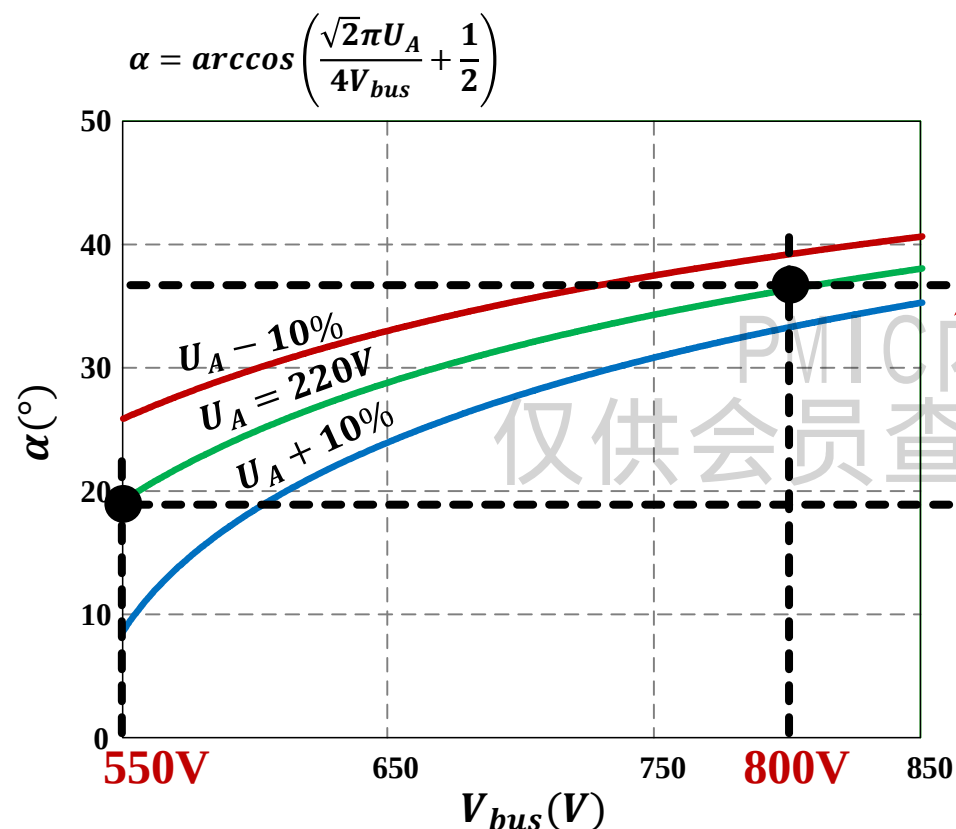
三相MISN-PFC变换器的优化设计研究

3

三相MISN-PFC变换器的极轻载控制研究

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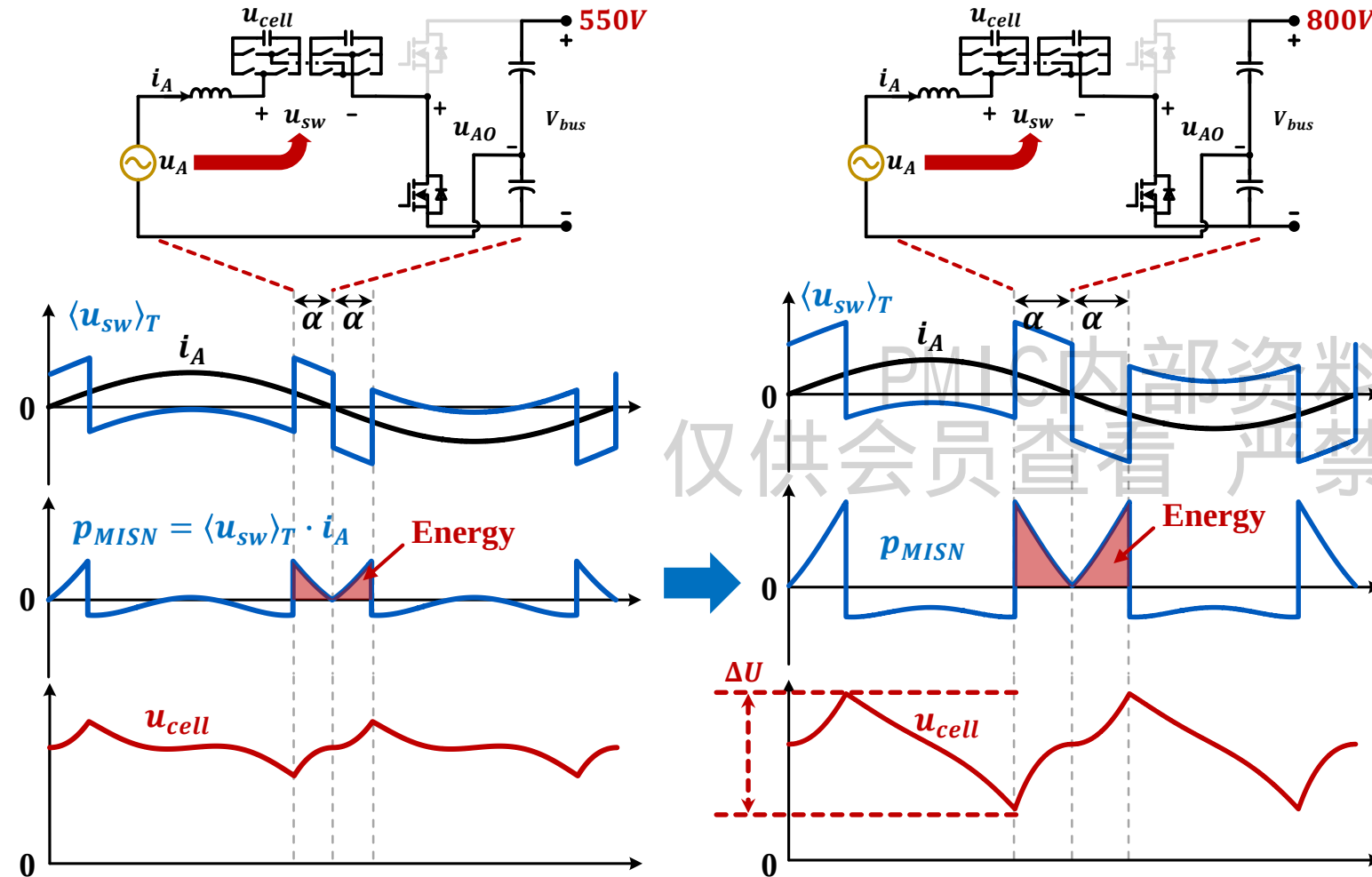




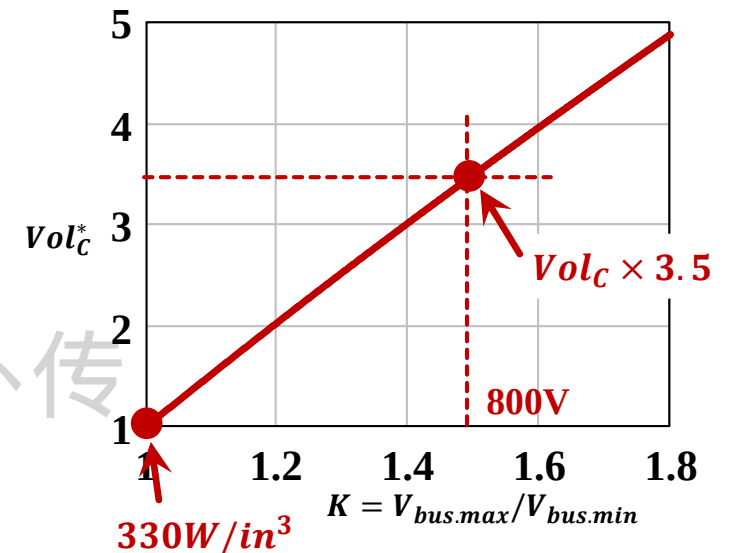
Large DC Bus Voltage Leads to Large Operating Value of α

The Increased MISN Capacitors' Volume due to Large Output Voltage Range

➤ Charing Mode of MISN Module



➤ Mathematical model for MISN Capacitor Volume



$$Vol_C^*(K) = \frac{Vol_C(K \cdot V_{bus.min})}{Vol_C(V_{bus.min})}$$

$$Vol_C = \frac{2P}{\omega E_D \Delta U} \left(2\alpha - \sin(2\alpha) - \frac{\pi(\cos\alpha - 1)}{2\cos\alpha - 1} \right)$$

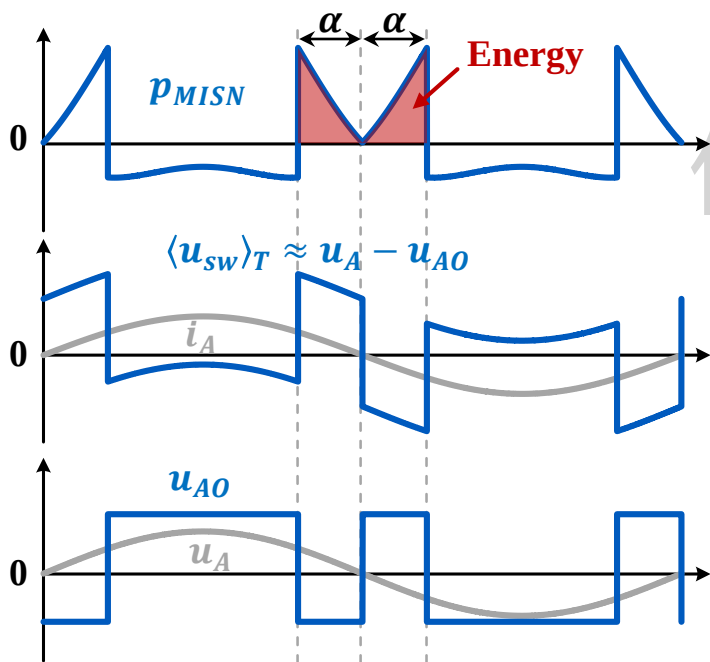
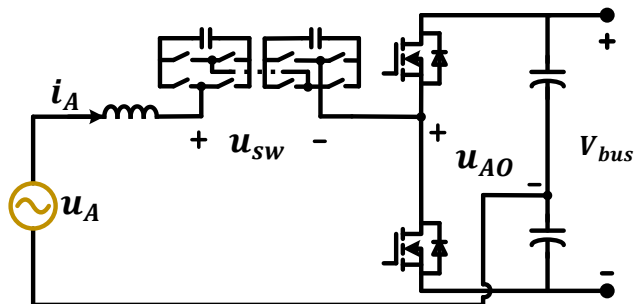
$$\alpha(K) = \arccos \left(\frac{\sqrt{2}\pi U_A}{4K \cdot V_{bus.min}} + \frac{1}{2} \right)$$

$$\Delta U = 20\%$$

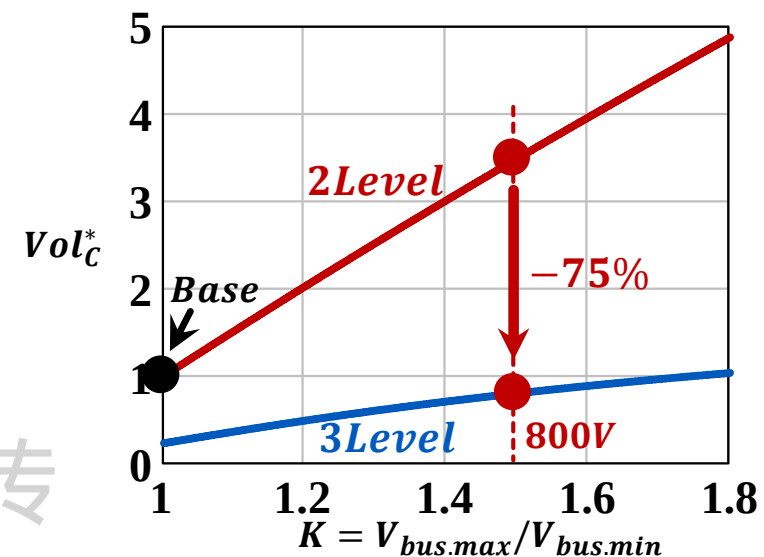
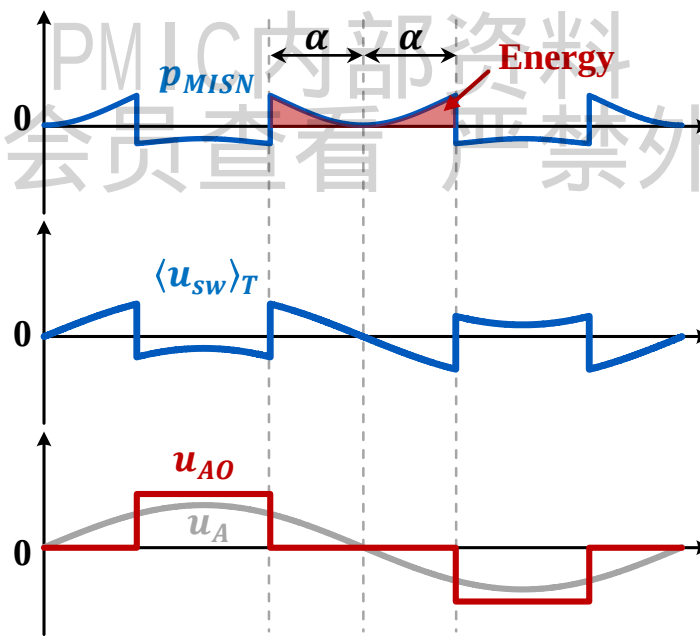
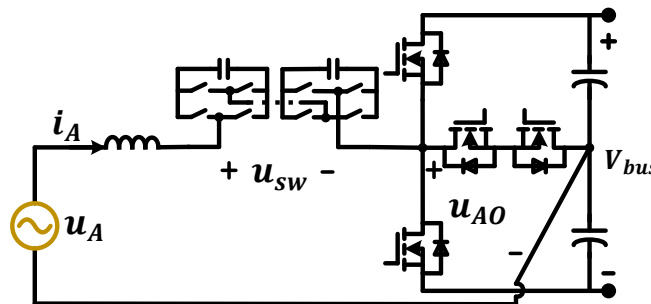
Larger capacitance is required

Reduce Volt-second of MISN Module by 3-level LF-bridge

➤ 2-level LF-bridge



➤ T-type 3-level LF-bridge

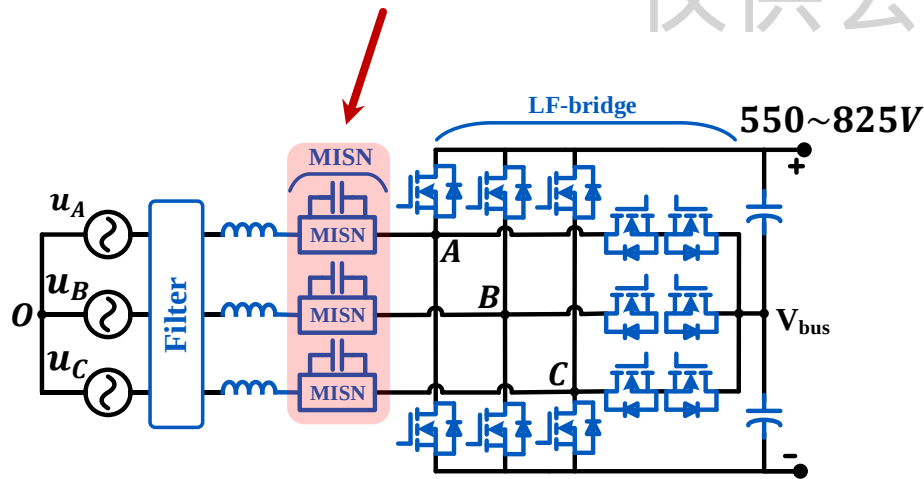
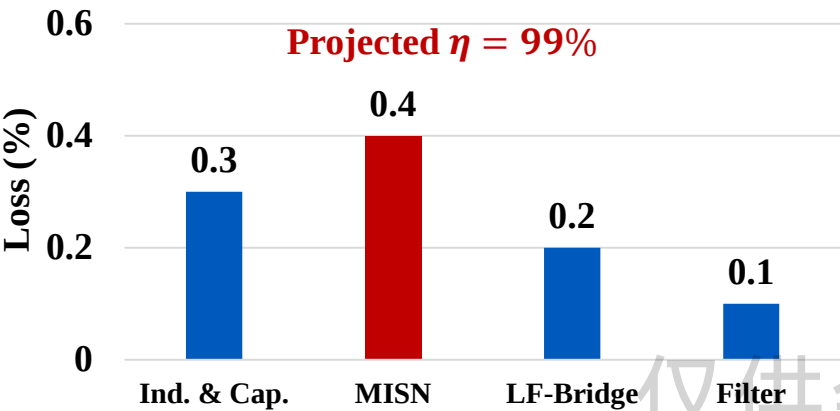


$$Vol_{C.2level}^* = \frac{Vol_{C.2level}(K \cdot V_{bus.min})}{Vol_{C.2level}(V_{bus.min})}$$

$$Vol_{C.3level}^* = \frac{Vol_{C.3level}(K \cdot V_{bus.min})}{Vol_{C.2level}(V_{bus.min})}$$

T-type 3-level LF-bridge
is adopted

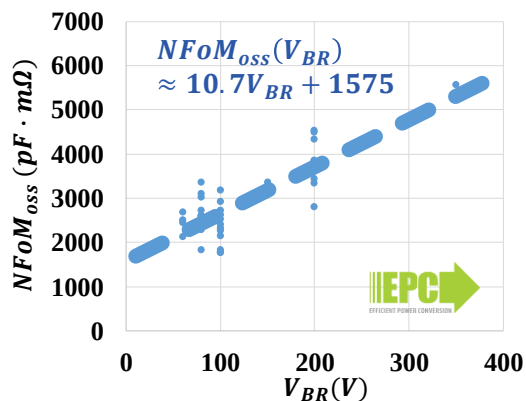
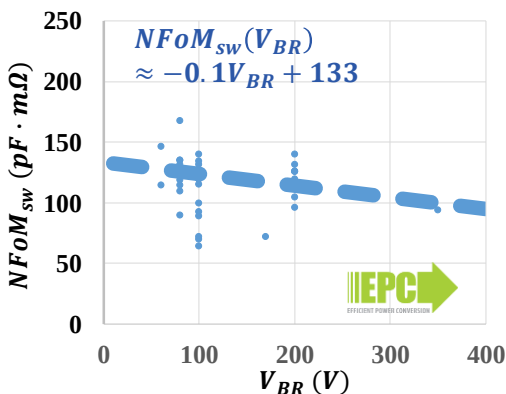
➤ The Loss Distribution at 10kW 800V_{dc}



➤ Minimum Loss Model of MISN Module (GaN)

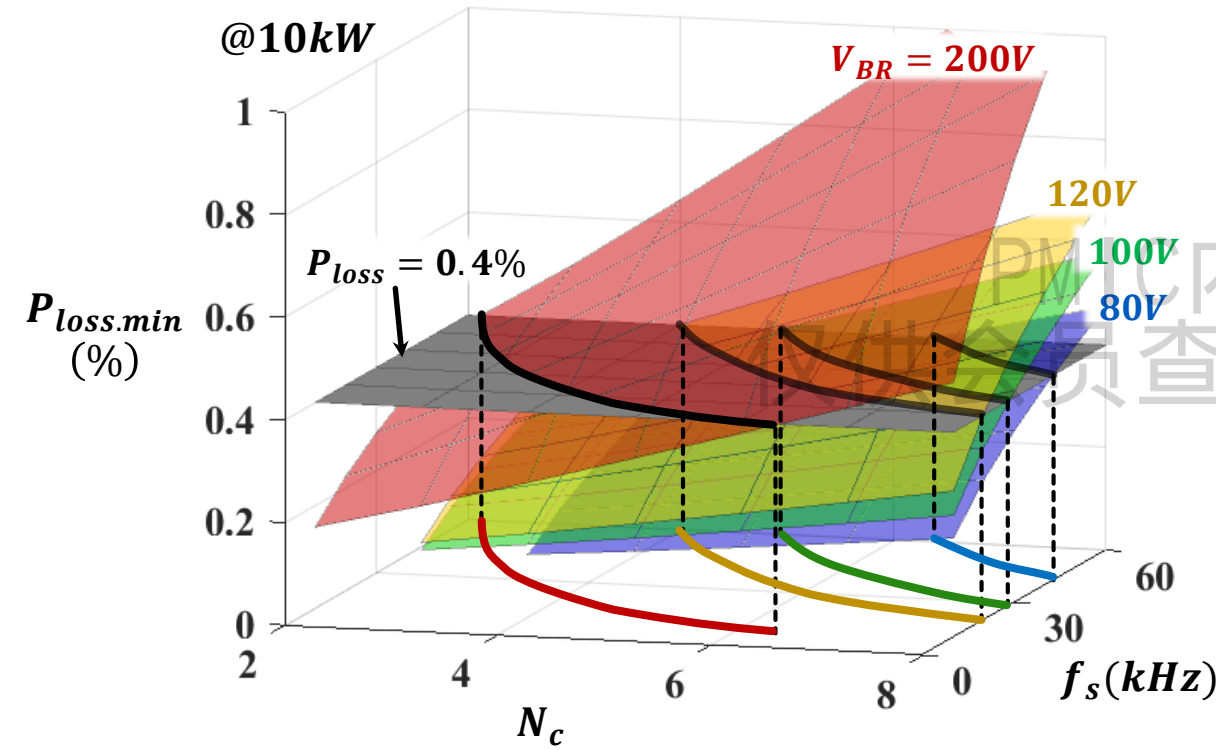
$U_{c.total} \rightarrow 0.7 N_c V_{BR}$

$$P_{Loss.min}(N_c, f_s, V_{BR}) = 4(U_{c.total}) I_{in} \sqrt{k_{temp} k_{dyn} (k_{sw} I_{in} NFoM_{sw} + NFoM_{oss}) f_s}$$
$$= 4(0.7 V_{BR} N_c) I_{in} \sqrt{k_{temp} k_{dyn} (k_{sw} I_{in} NFoM_{sw}(V_{BR}) + NFoM_{oss}(V_{BR})) f_s}$$

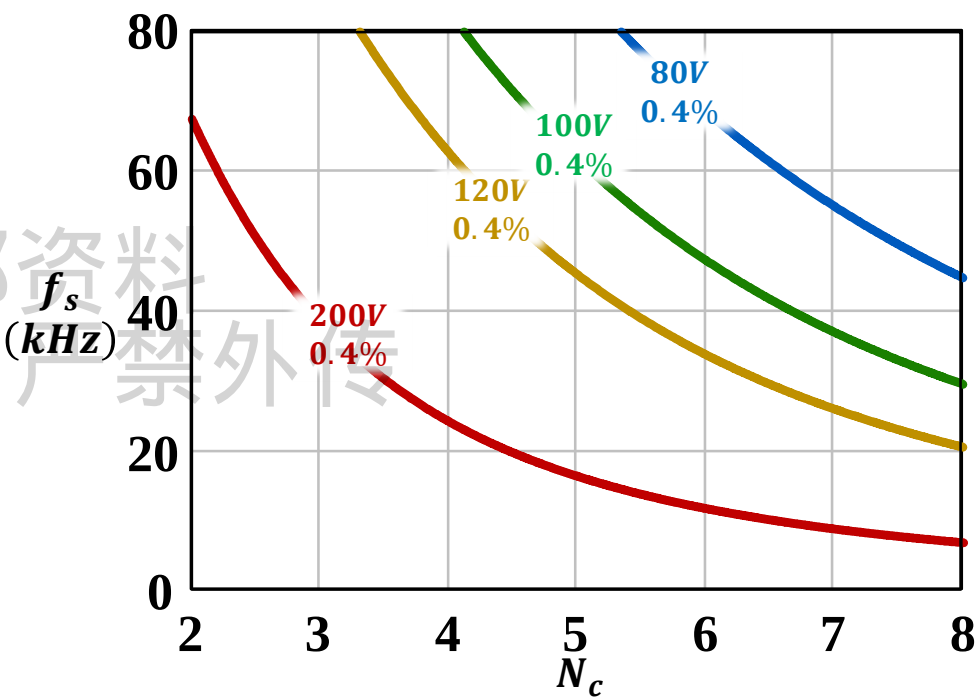


The Limitation for f_s based on the Projected Loss

➤ $P_{Loss.min} = f(N_c, f_s, V_{BR})$

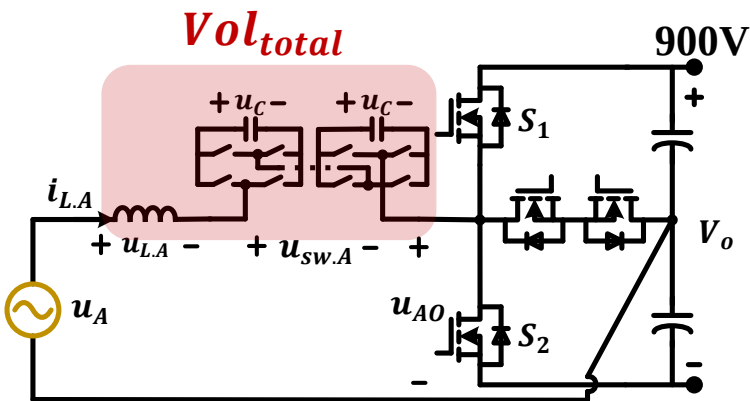


➤ The Limitation for f_s



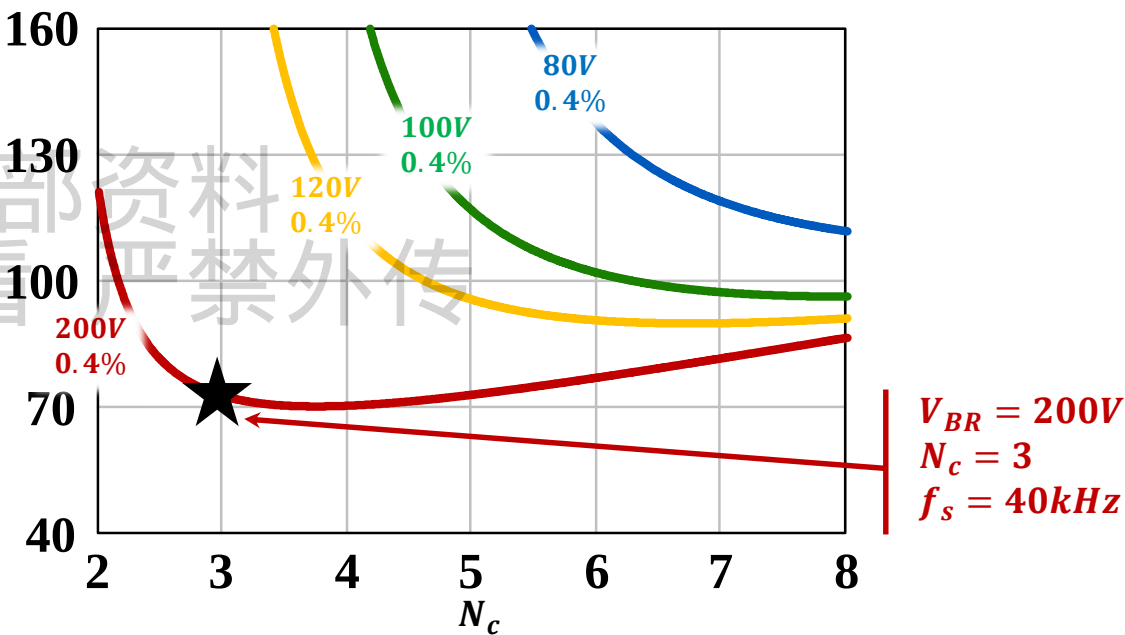
$$f_s(N_c, V_{BR}) = \frac{1}{k_{temp}k_{dyn}(k_{sw}I_{in}NFoM_{sw}+NFoM_{oss})} \left(\frac{P_{loss.exp}}{4U_{c.total}^{avg}I_{in}} \right)^2$$

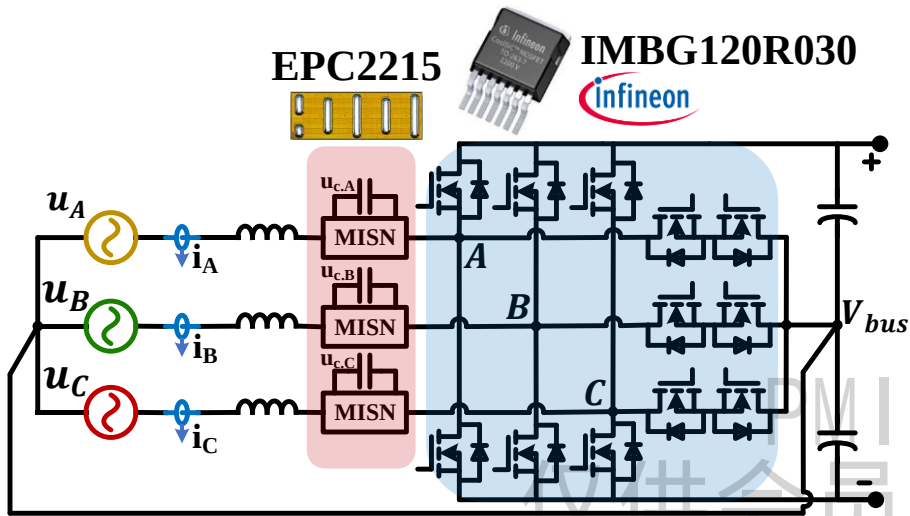
• $N_c \cdot V_{BR} \geq U_{c.total}^{valley} = \sqrt{2}U_A \sin\alpha$



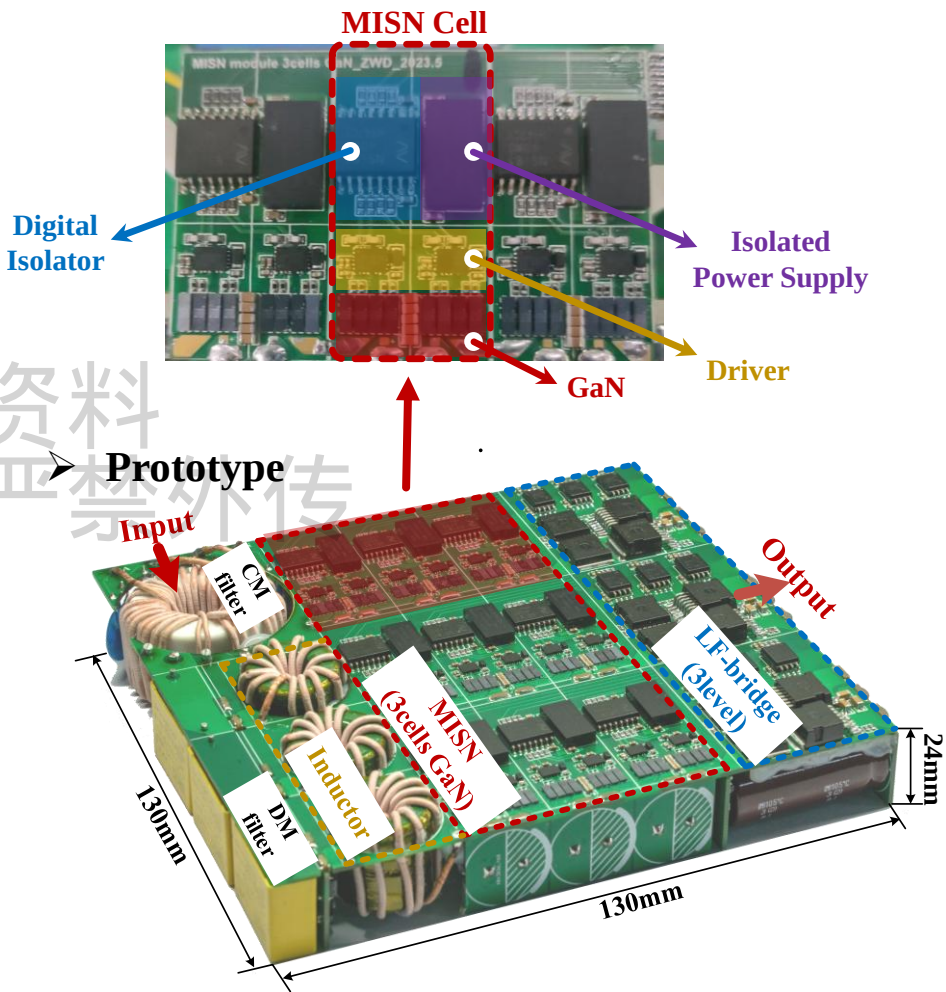
$$Vol_{total} = Vol_L + Vol_C + Vol_{cell}$$

- Inductor Volume: (AP Method)
$$\begin{cases} L(N_c, f_s, V_{BR}) = \frac{0.7 V_{BR}}{8 N_c f_s \Delta i_{pp}} \\ Vol_L = k_L \left(\frac{L I_{peak} I_{RMS}}{k_w J B_m} \right)^4 \end{cases}$$
- Capacitor Volume:
$$Vol_C(N_c, V_{BR}) = \frac{\frac{1}{2} (1.2 C_{eq.min}) (V_{BR})^2}{E_D} N_c$$
- MISN Cell Volume:
$$Vol_{cell} = K \cdot N_c$$

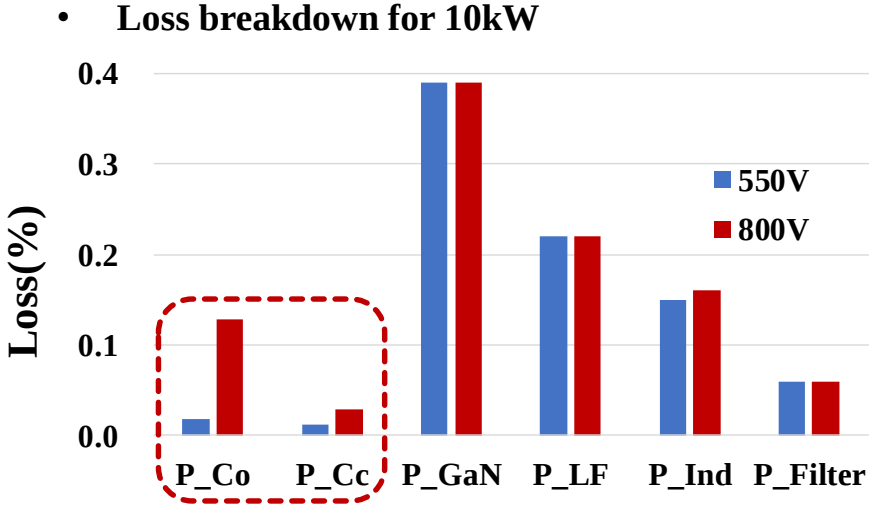
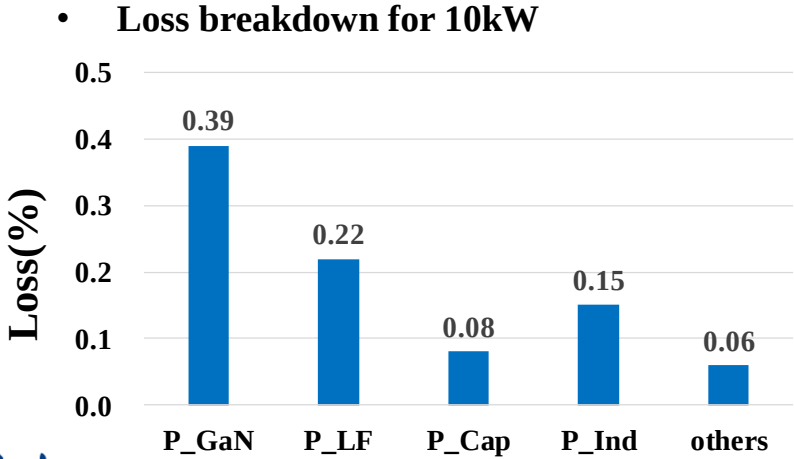
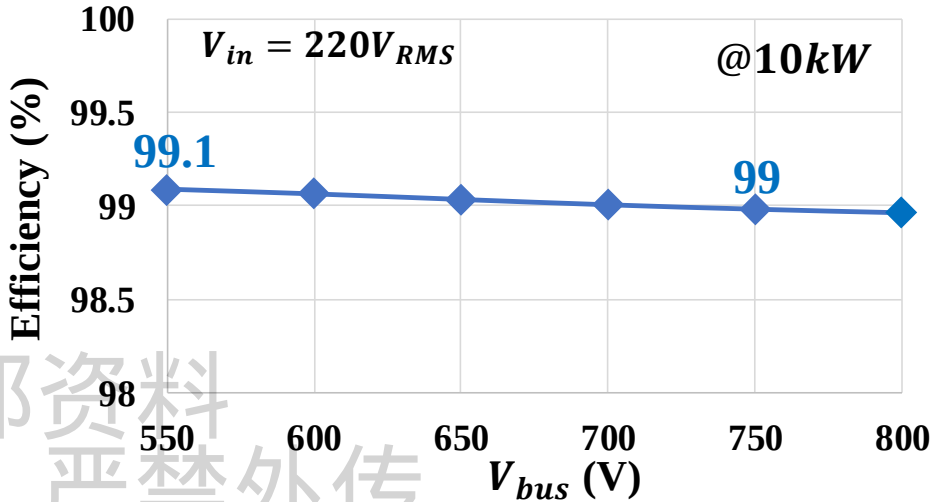
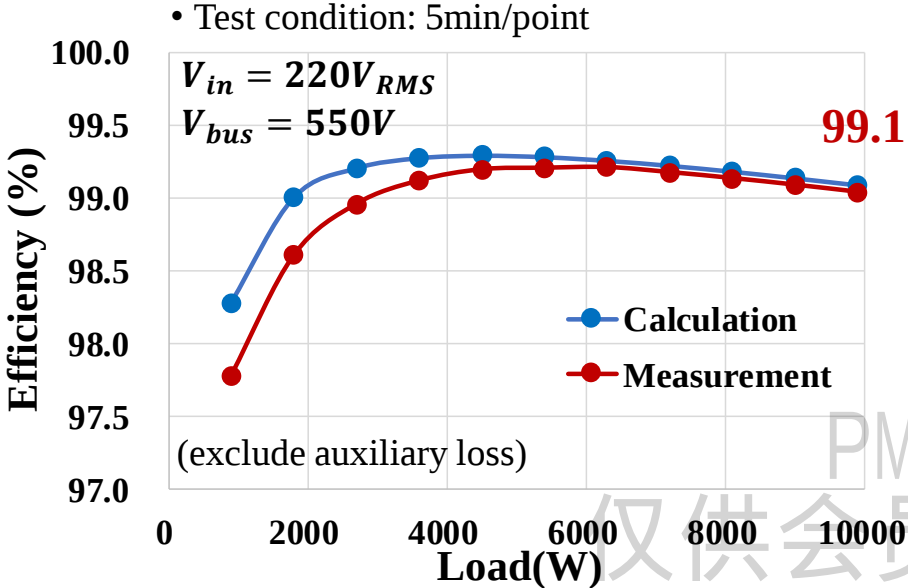




Parameter	Value
Power	10kW
Input Phase Voltage	$220V_{RMS} \pm 10\%$
Output Voltage	550V~900V
MISN Voltage	$3 \times 120V$
Frequency (MISN)	40kHz



Power Density: 400W/in³



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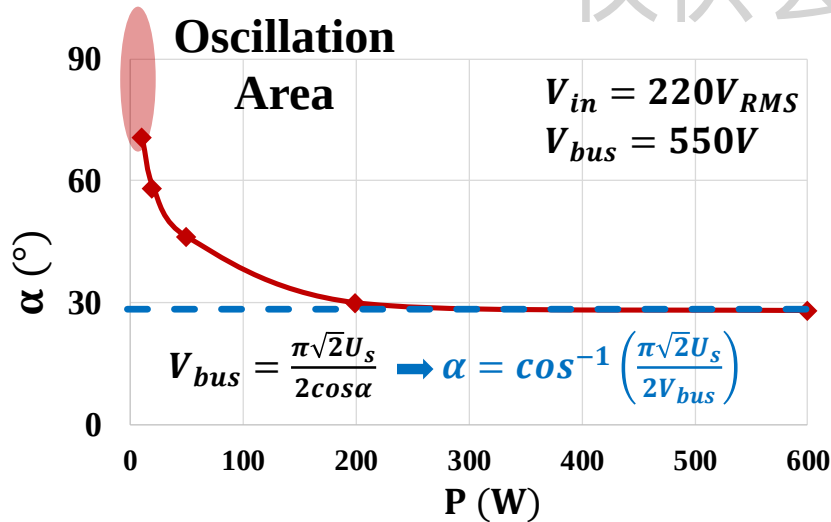
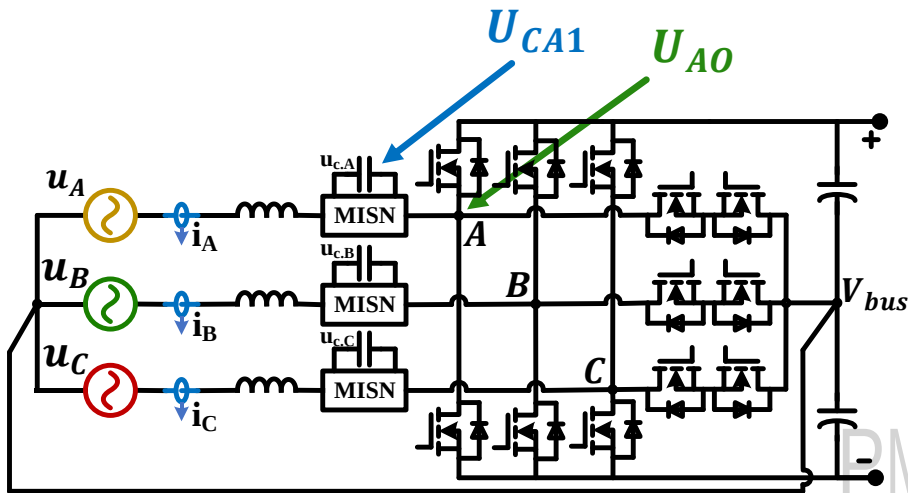
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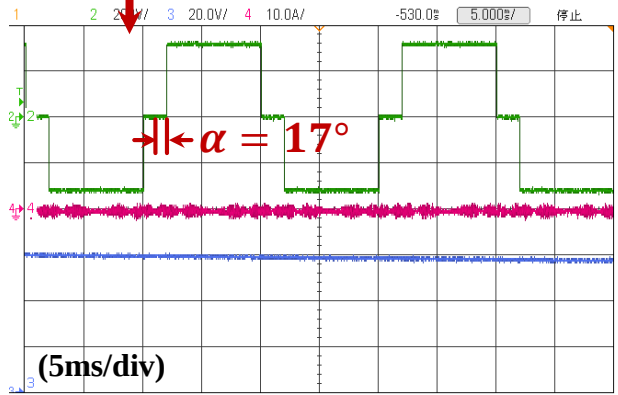
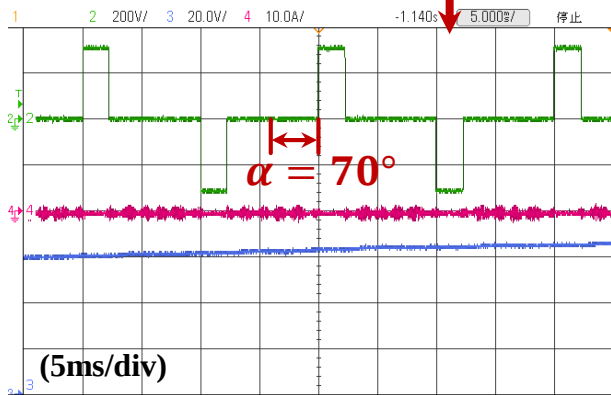
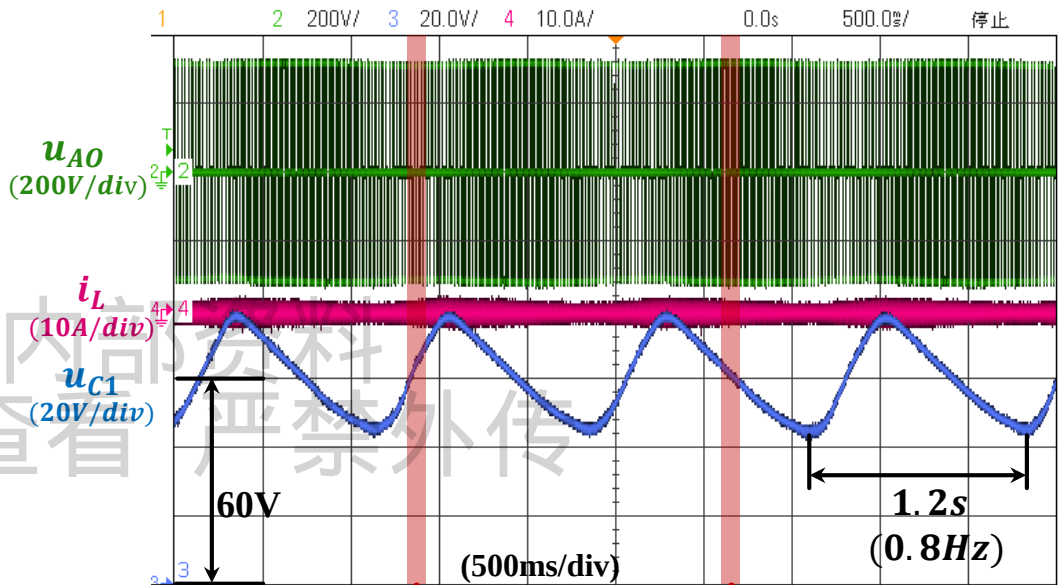
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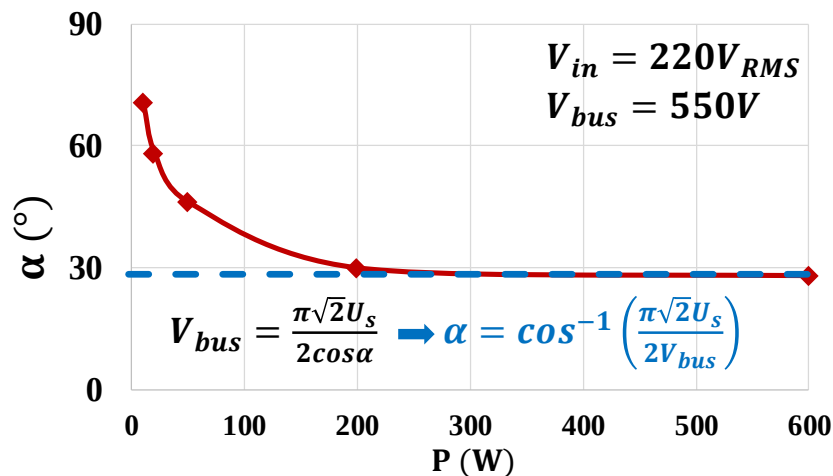
Oscillation Phenomenon When α Close to 90°



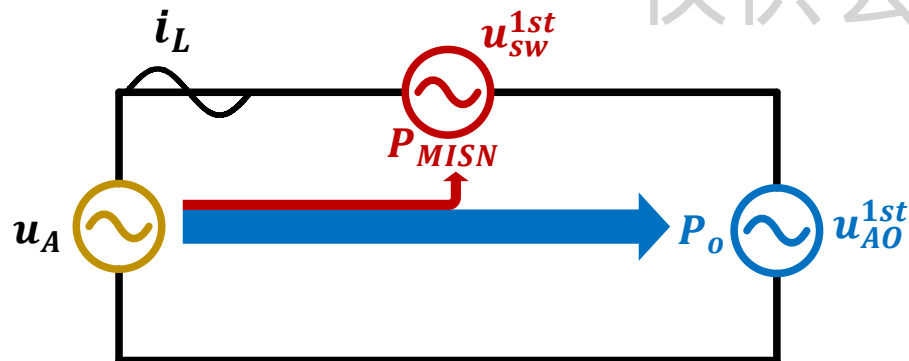
➤ The Oscillating of MISN Voltage Loop at No Load



The Fundamental Voltage U_{AO}^{1st} is Reduced at Light Load



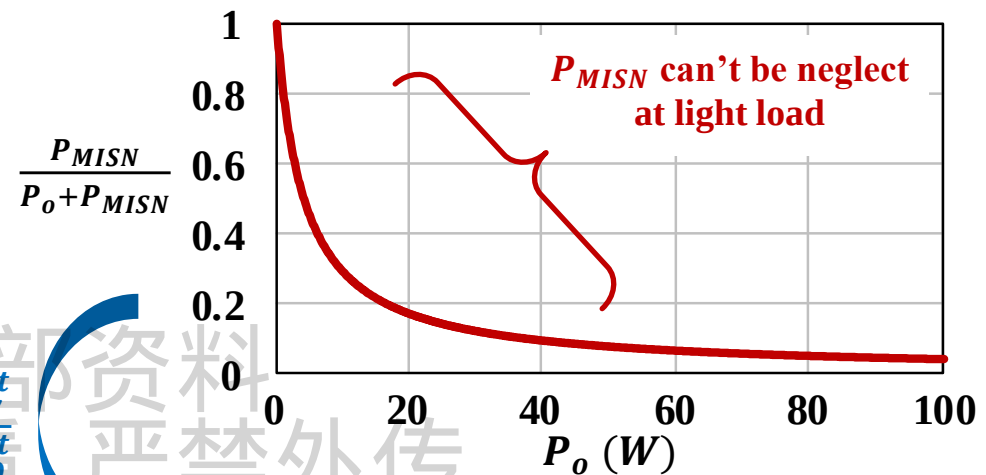
Fundamental Equivalent Circuit



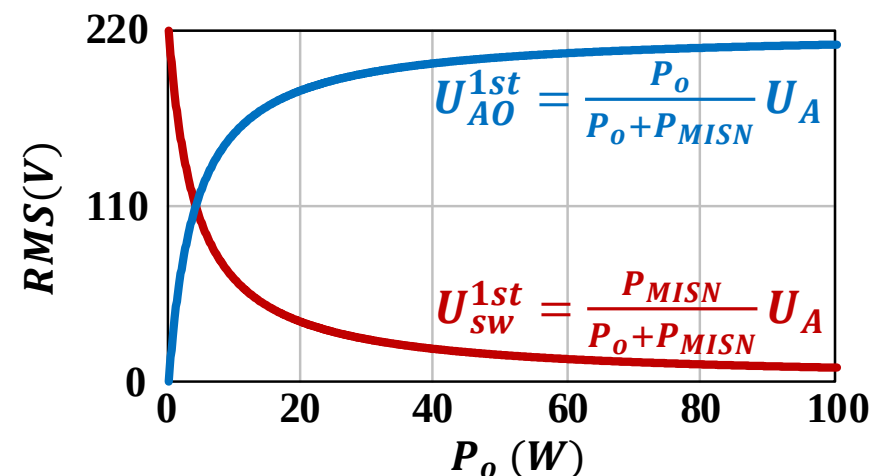
Assume $P_{MISN} \approx 0 \rightarrow u_{AO}^{1st} = u_A \rightarrow V_{bus} = \frac{\pi\sqrt{2}U_A}{2\cos\alpha}$

$\alpha = \cos^{-1}\left(\frac{\pi\sqrt{2}U_s}{2V_{bus}}\right)$

The Proportion of P_{MISN} ($P_{MISN} \approx P_{GaN} + P_{cap}$)

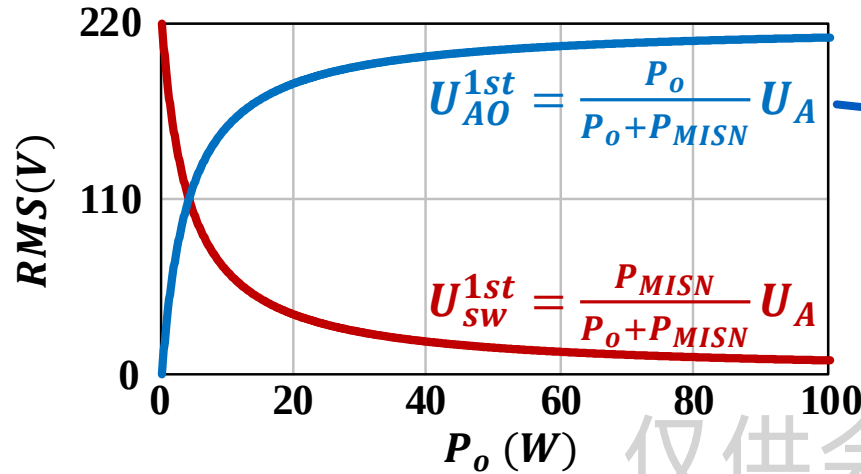


The Proportion of Voltage ($U_{AO}^{1st} + U_{sw}^{1st} = U_A$)

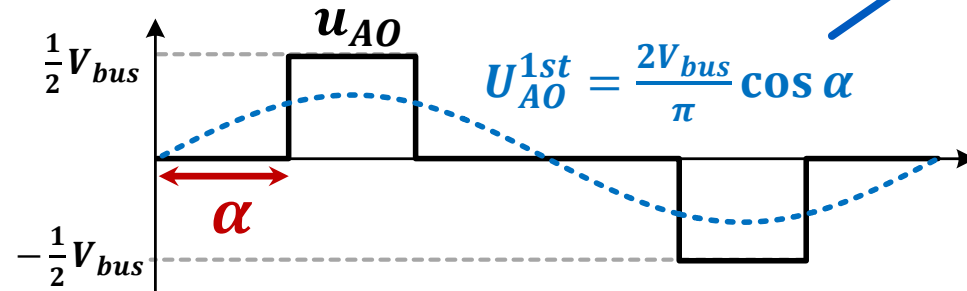


The Increase Proportion of P_{MISN} at Light Load Resulting in the Increase of α

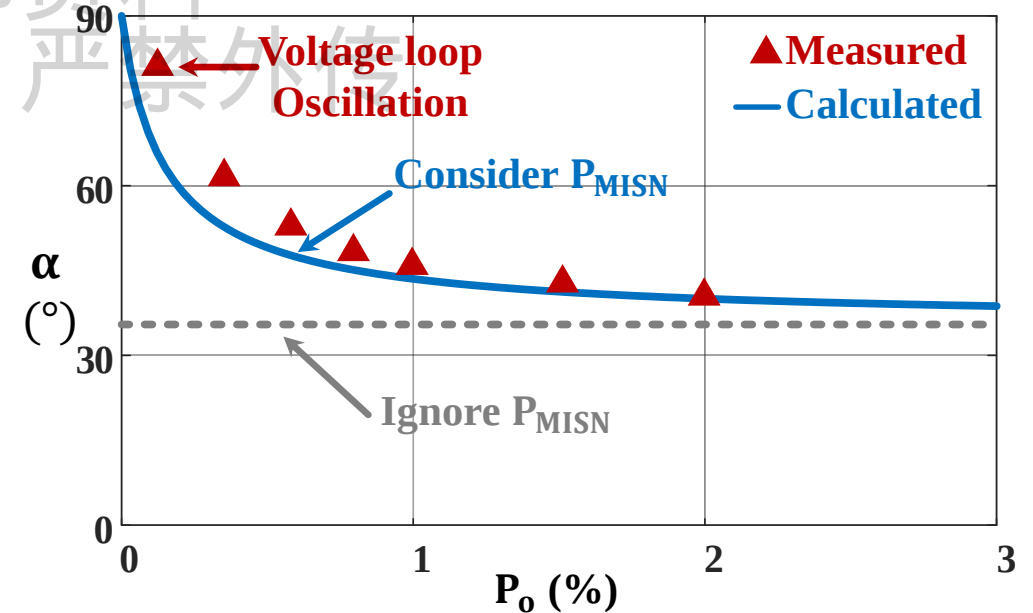
➤ The Proportion of Voltage



$$\alpha = \cos^{-1} \left(\frac{\pi \sqrt{2} U_A}{2 V_{bus}} \cdot \frac{P_o}{P_o + P_{MISN}} \right)$$

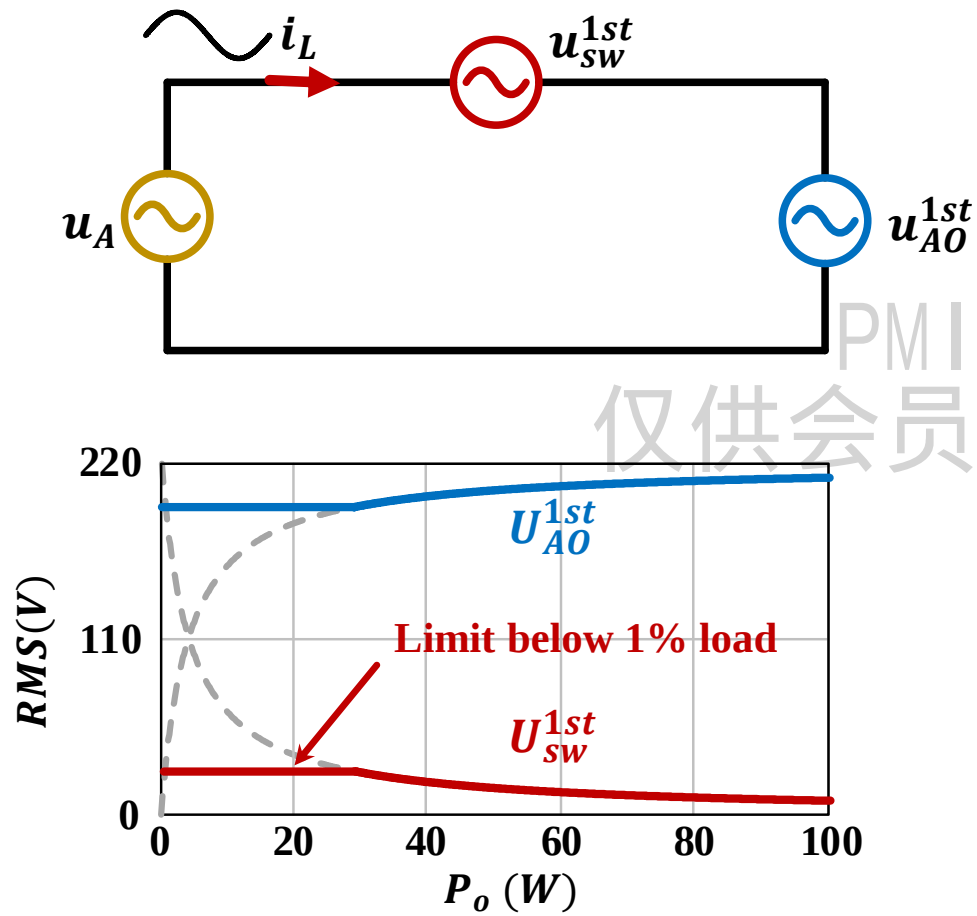


$$U_{AO}^{1st} \downarrow \rightarrow \alpha \uparrow$$

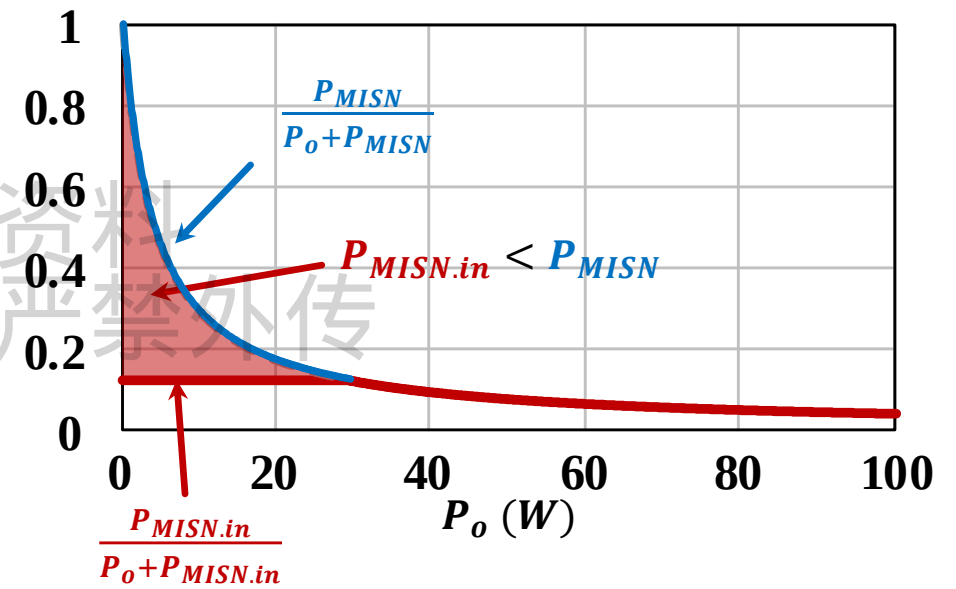


The Input Power $P_{MISN.in}$ can't Meet with Power Consumption P_{MISN} when α is Limited

➤ Fundamental Equivalent Circuit



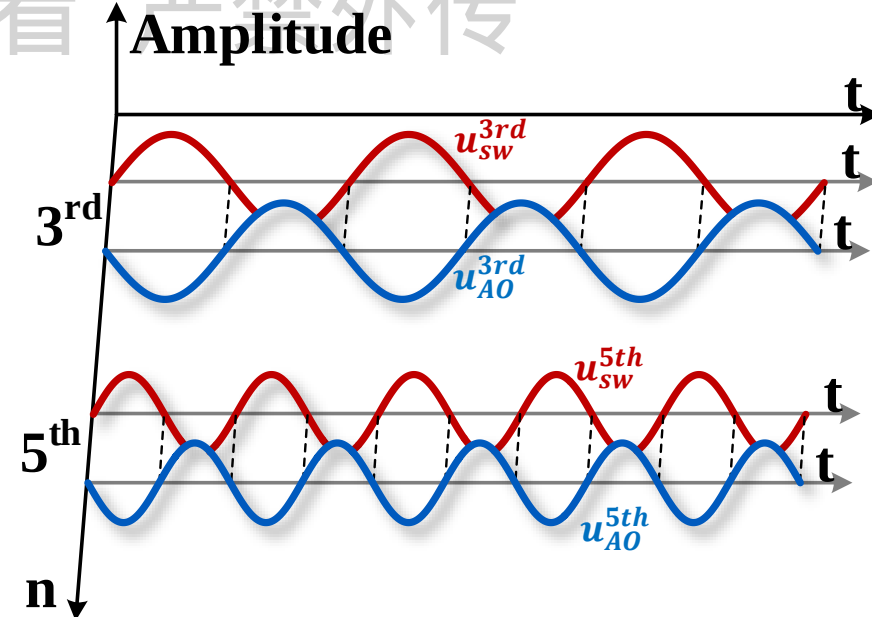
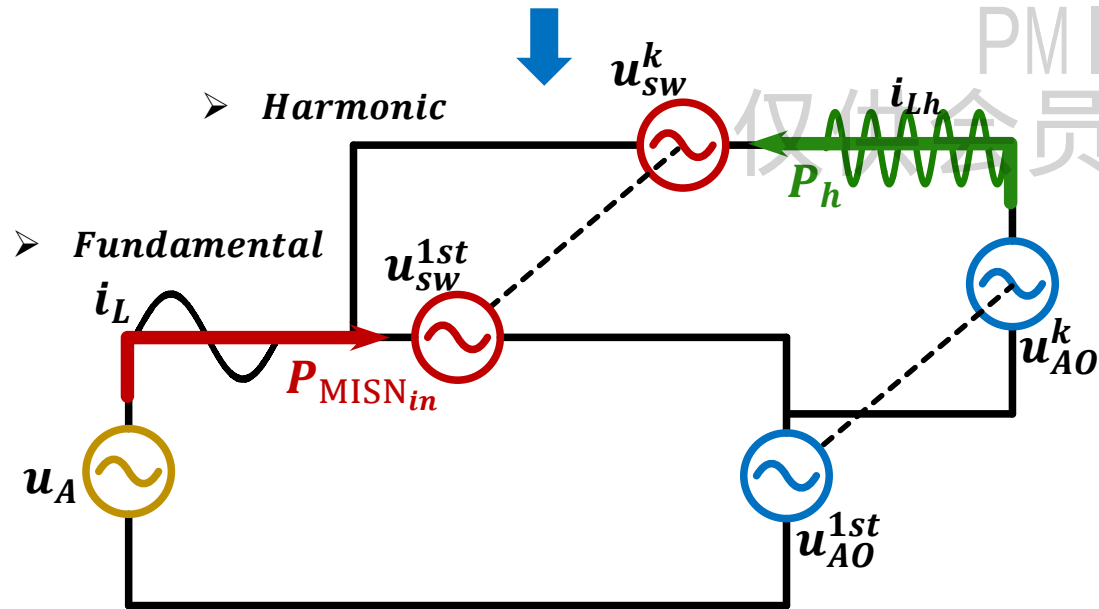
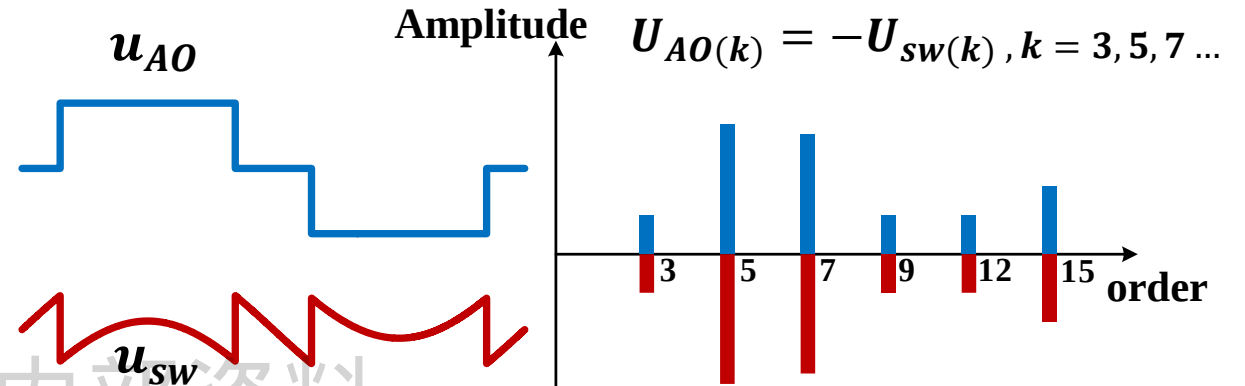
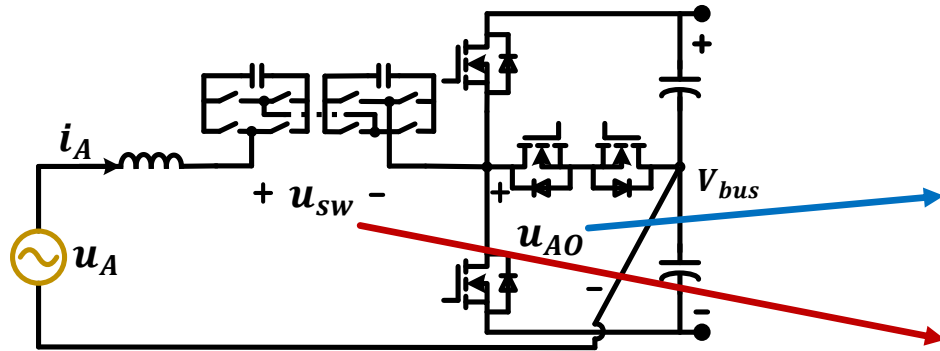
➤ The Proportion of P_{MISN}



$$P_{MISN} \approx P_{GaN} + P_{cap}$$

$$P_{MISN.in} \approx U_{sw}^{1st} \cdot I_L$$

Power Compensation based on the Harmonic Current Injection



$$P_{MISN.in} + P_h = P_{MISN}$$

[illegible]

1 200V/ 2 10.0V/ 3 200V/ 4 10.0A/ 7.620s 2.000% 停止

2ms/div

U_c 10V/div

i_L 10A/div

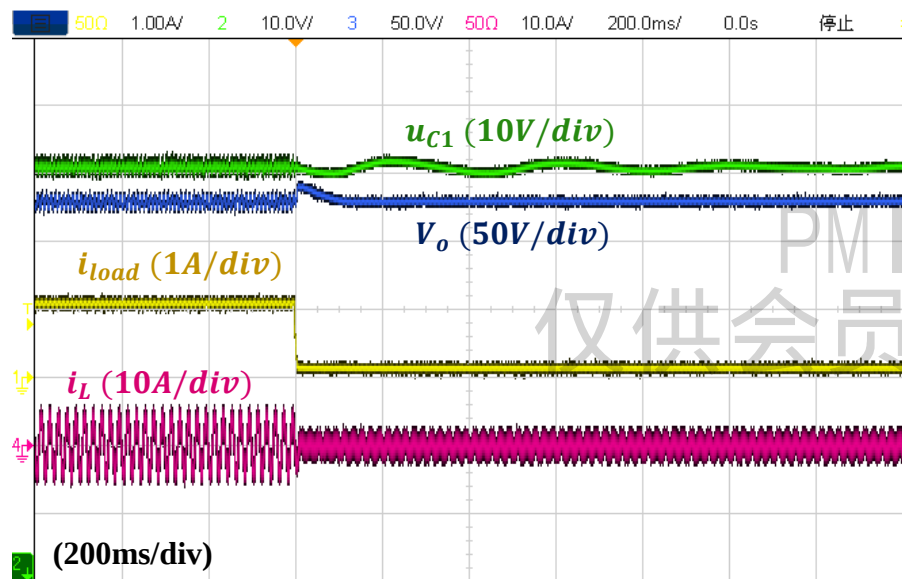
u_s 200V/div

u_{AO} 200V/div

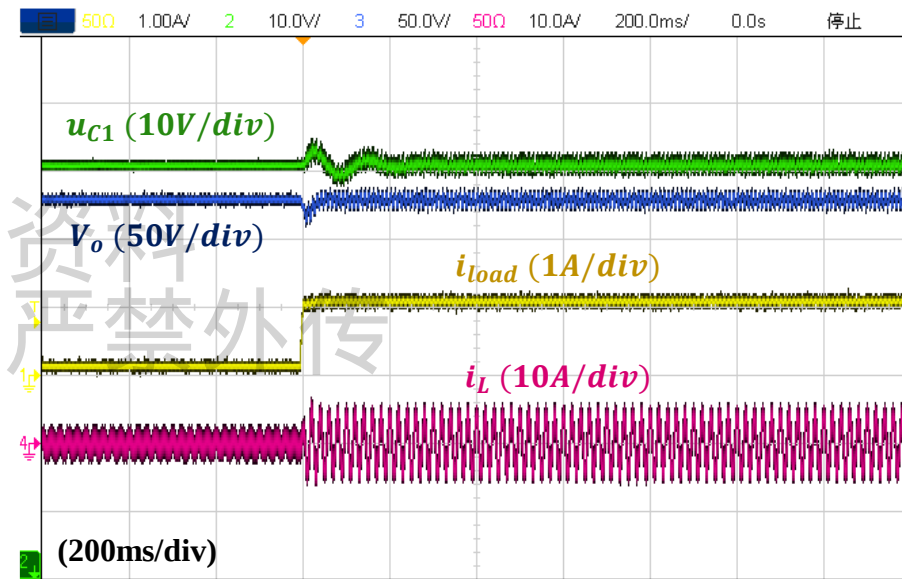
$\alpha = 43^\circ$

- Eq. 1: $\alpha_0 = K\alpha = \arccos\left(\frac{\sqrt{2}\pi U_s}{4V_o}\right)$

➤ From 10% load to No load



➤ From No load to 10% load



创新点一 暂态补偿控制策略

- 针对现有模块化的多电平PFC拓扑多母线导致系统架构复杂且母线电容体积大的问题，提出一种新型的模块化感性开关网络PFC变换器和相应的控制策略，大幅减小电感伏秒，提升变换器功率密度，并实现高度模块化多电平单元以及单直流母线结构。

创新点二 多变量优化设计方法

- 针对多电平PFC变换器电路缺乏系统性设计方法的问题，本文提出一种创新的优化设计策略，全面考虑MISN-PFC变换器的损耗以及体积，高效地根据效率目标确定变换器最优功率密度所需电路参数，设计方法的指标预测误差小于10%。

创新点三 极轻载控制策略

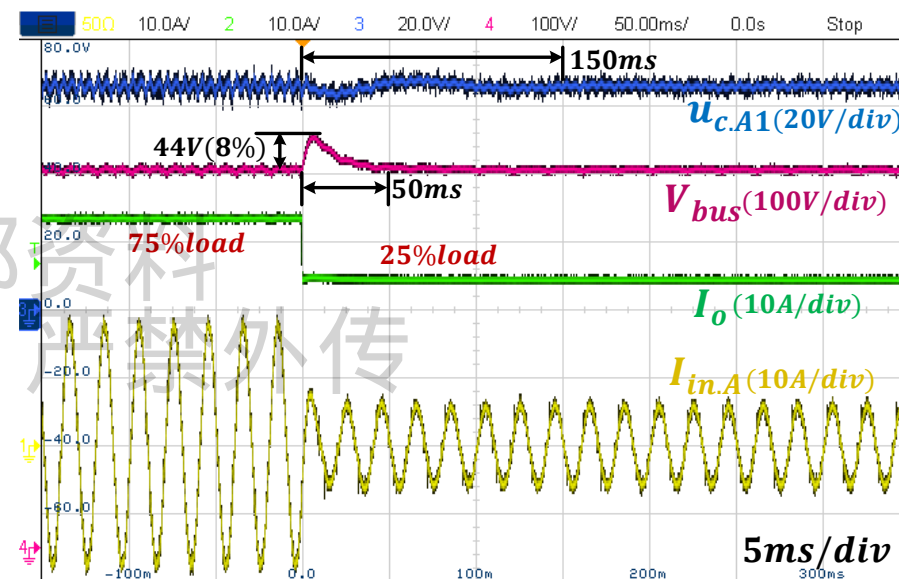
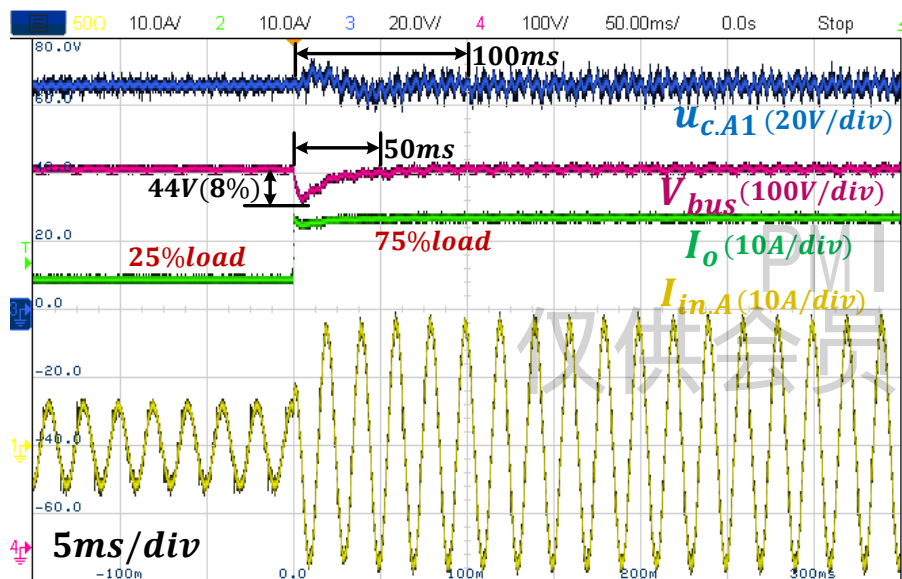
- 针对MISN-PFC在极轻载工况下工频整流桥斩波角趋于饱和导致电压环路震荡的问题，本文建模分析工频频率下变换器的功率传输路径，揭示极轻载下MISN模块损耗导致斩波角增大的原理，在此基础上提出一种基于谐波功率补偿的极轻载控制策略，通过谐波频段维持MISN模块功率平衡，实现电压环路稳定。



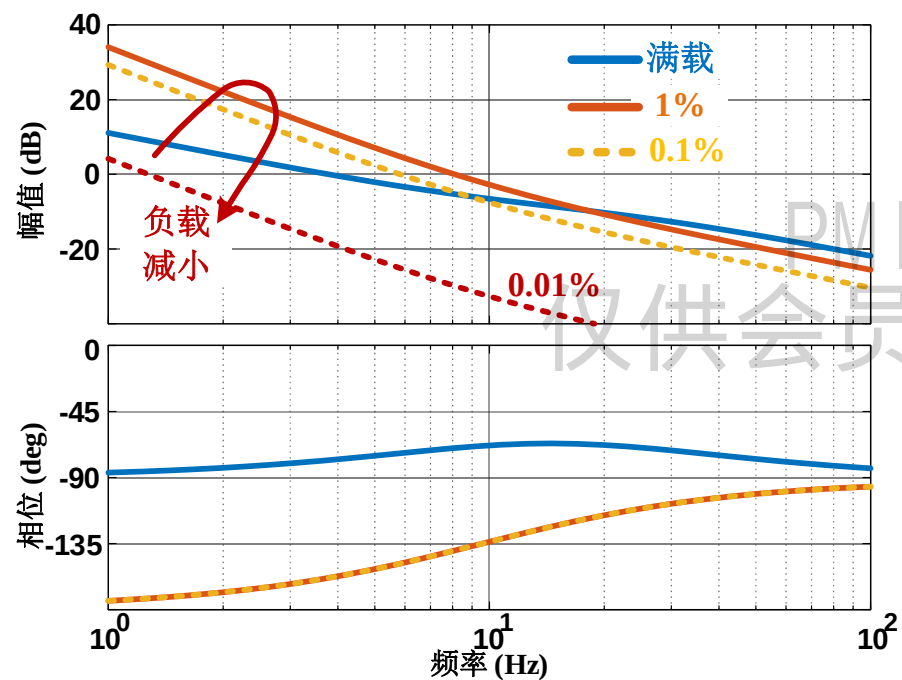
1. 当输入电压三相不平衡时，如何处理？当输入电压掉电再恢复时，如何能够快速锁相并保证驱动时序的正确性？如果母线电容中点不接功率管，可以吗？
2. 请问可否使用磁集成磁心？
3. 怎么实现均流控制？
4. 请问功率因数可提高多少？

PMIC内部资料
仅供会员查看 严禁外传

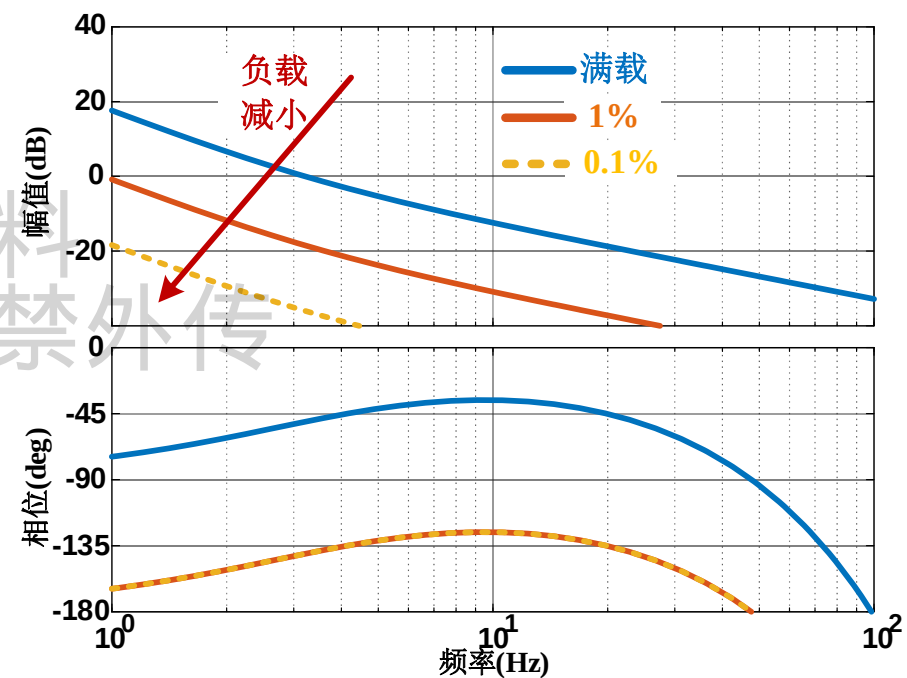


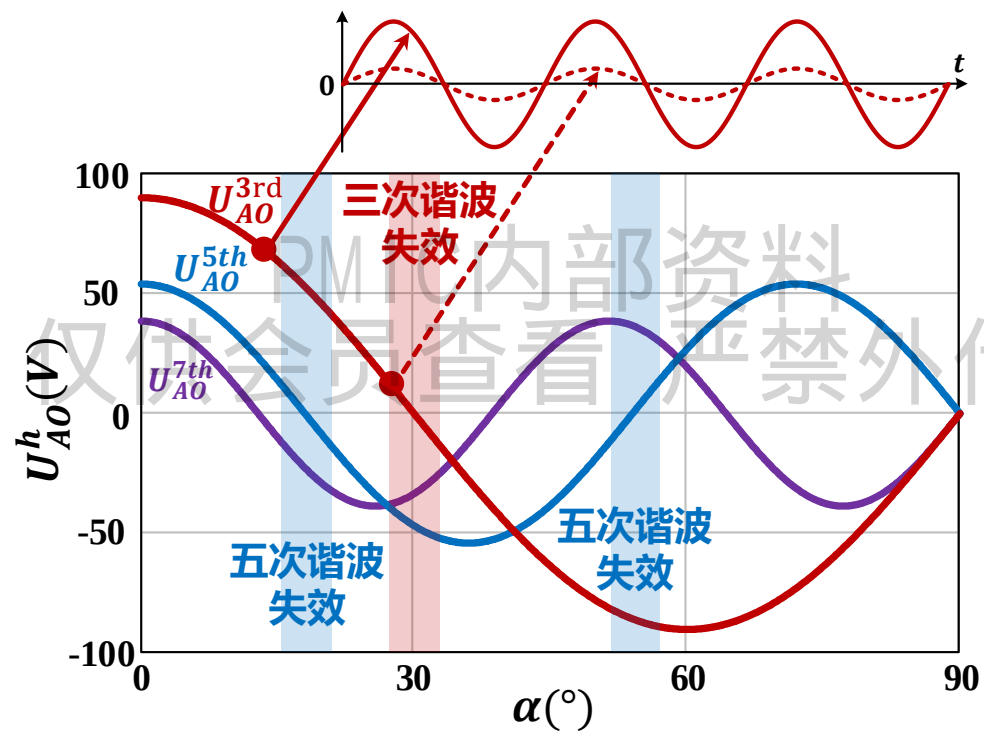


➤ Bode diagram for DC bus voltage loop



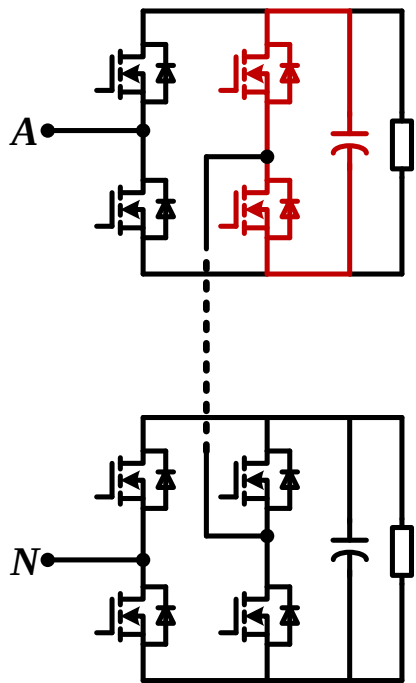
➤ Bode diagram for MISN voltage loop





Comparison for Basic Multilevel Topology

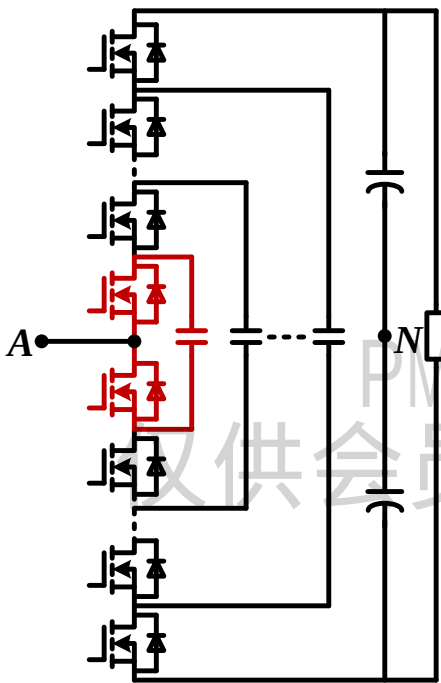
➤ CHB



✓ Good Modularity

! Multiple DC Bus
Complicated structure
Bulky Capacitor

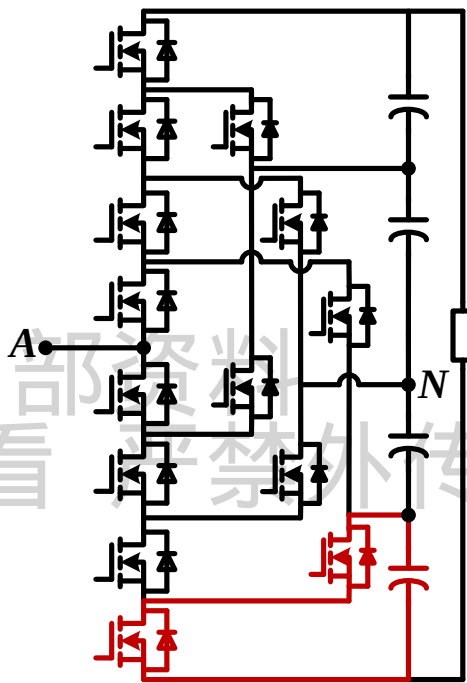
➤ FC



✓ Single DC Bus

! Bad Modularity
Short fault protect
Redundancy

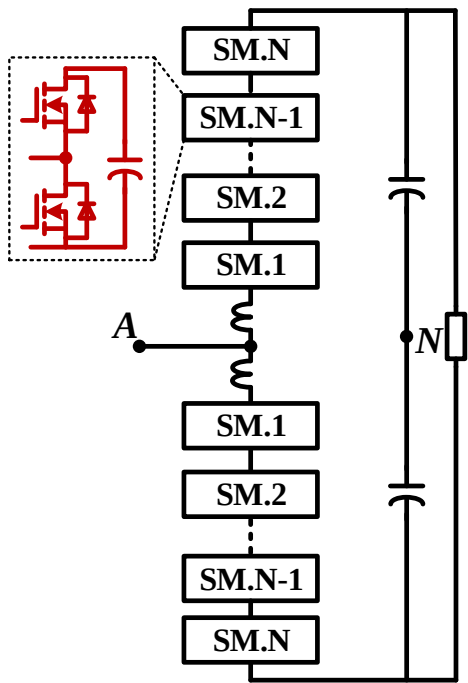
➤ ANPC



✓ Single DC Bus

! Bad Modularity
Redundancy
! More switches

➤ MMC



✓ Single DC Bus

✓ Good Modularity
! More switches
! More Capacitors
Larger capacitance

